

Experience with the new Oxford-Danfysik cryo-pump

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Motivation: Rev C > Rev D

Simplify design (reduce production cost).

Reduce no. of second market components.

Move to pure PLC design.

Incorporate user experience:

J. Gonczy's (SERC) Input:

Re-design of LN2 input system:

reduce turbulence and pressure perturbation associated with onset of vessel fill.

Improve thermal isolation of pump buffer chamber.

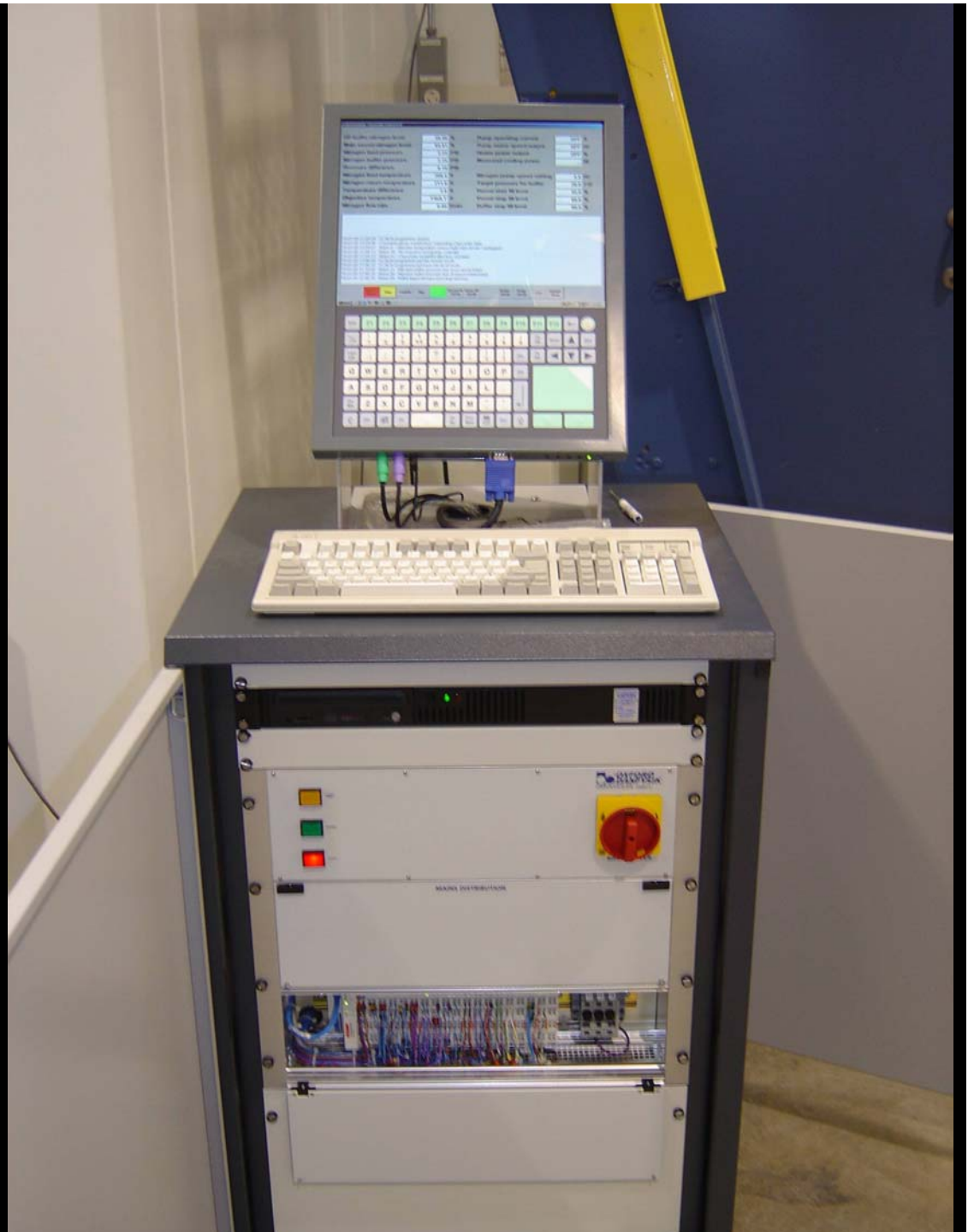
External loop shunt.

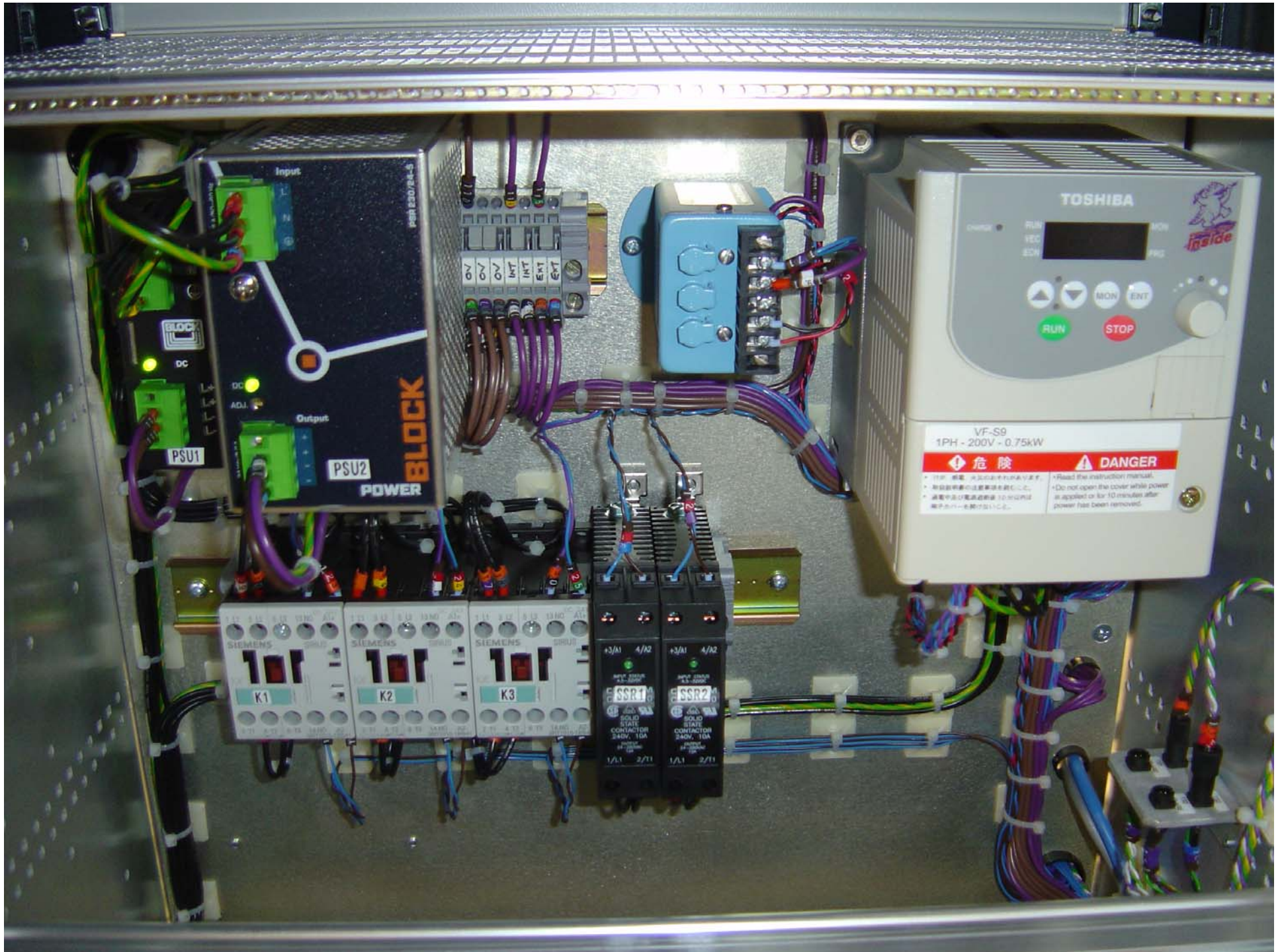
Additional over-pressure protection – avoid pressure disc ruptures.

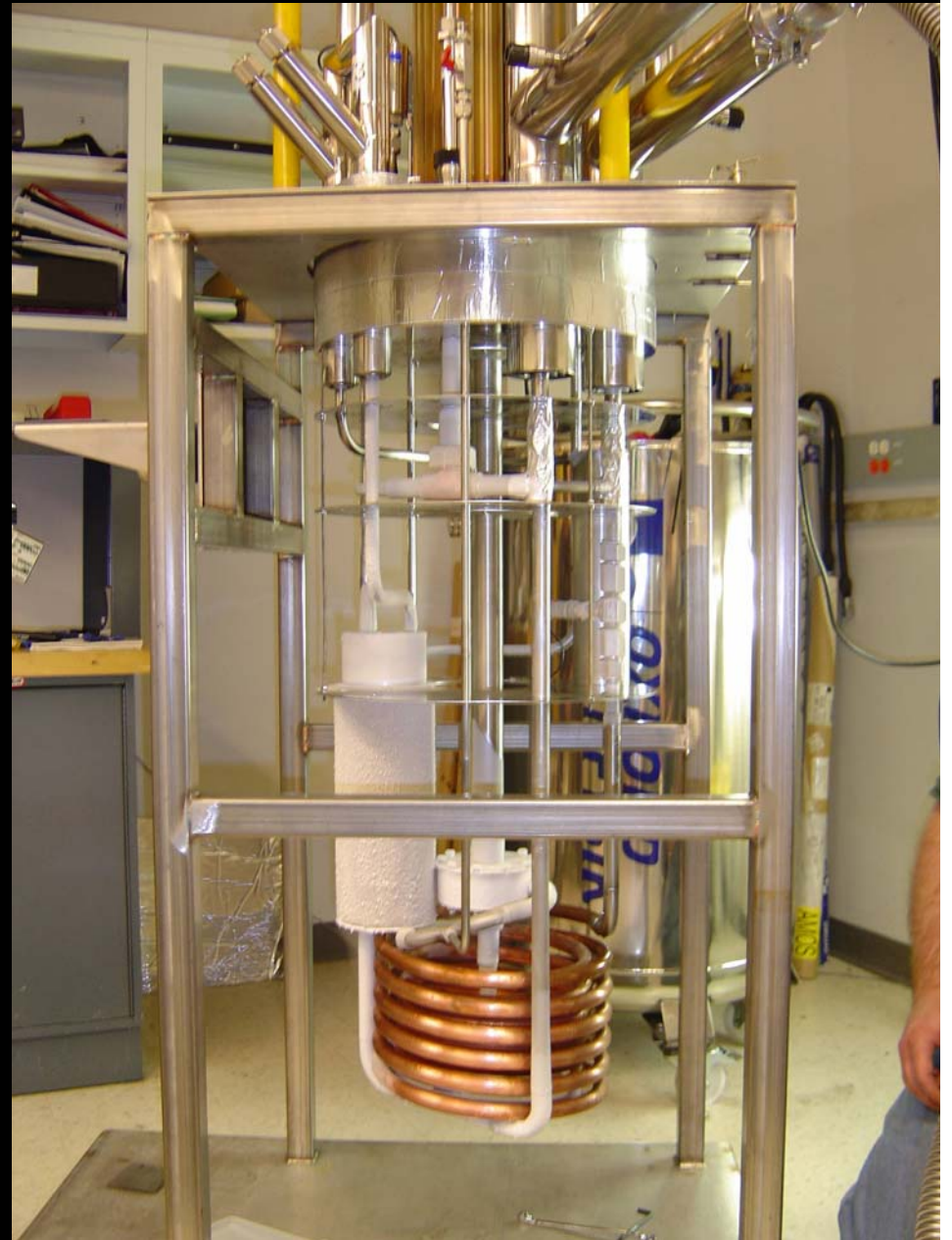
Rev C Controller



Rev D Controller









(%) 44.5 HP BUFFER LEVEL	(A) .698 PUMP CURRENT
(%) 65.4 MAIN VESSEL LEVEL	(Hz) 5 PUMP FREQUENCY
(PSI) 19.9 FEED PRESSURE	(%) 18.3 HEATER POWER
(PSI) 20.08 BUFFER PRESSURE	(W) -9.9E-2 COOLING POWER
(PSI) 0.18 PRESSURE DIFFERENTIAL	(Hz) 5 PUMP SET FREQUENCY
(K) 208.7 FEED TEMP	(PSI) 20 BUFFER P TARGET
(K) 211.6 RETURN TEMP	(%) 55 VESSEL START FILL
(K) 2.90 TEMP DIFFERENTIAL	(%) 60 VESSEL STOP FILL
(L/MIN) -1 LN2 FLOW	(%) 80 BUFFER STOP FILL LEVEL

```
server_slot = socket(AF_INET, SOCK_STREAM, 0);
```

```
server_slot.sin_family = AF_INET;           // Address family to use
server_slot.sin_port = htons((short)port_num); // Port num to use (7243)
server_slot.sin_addr.s_addr = inet_addr(ip_addr); // IP address to use
```

```
// connect to socket
retcode = connect(server_slot, (struct sockaddr *)&server_slot,
                  sizeof(server_slot));
```

```
if (retcode != 0)
{
    sprintf(in_buf, "server_socket_put ERROR - connect() failed");
    return -1;
}
```

```
retcode = setsockopt(server_slot, SOL_SOCKET, SO_RCVTIMEO, (char*)
                    &OptVal, sizeof(int));
```

```
// Send a GET to the server
strcpy(out_buf, outbuf);
byteSent = send(server_slot, outbuf, strlen(outbuf), 0);
```

```
// Receive from opened socket
retcode = recv(server_slot, in_buf, BUF_SIZE, 0);
in_buf[retcode+1]=0;
```

```
// Close open socket
closesocket(server_slot);
```

FORM of outbuf: "Rnn" where nn = 0...32