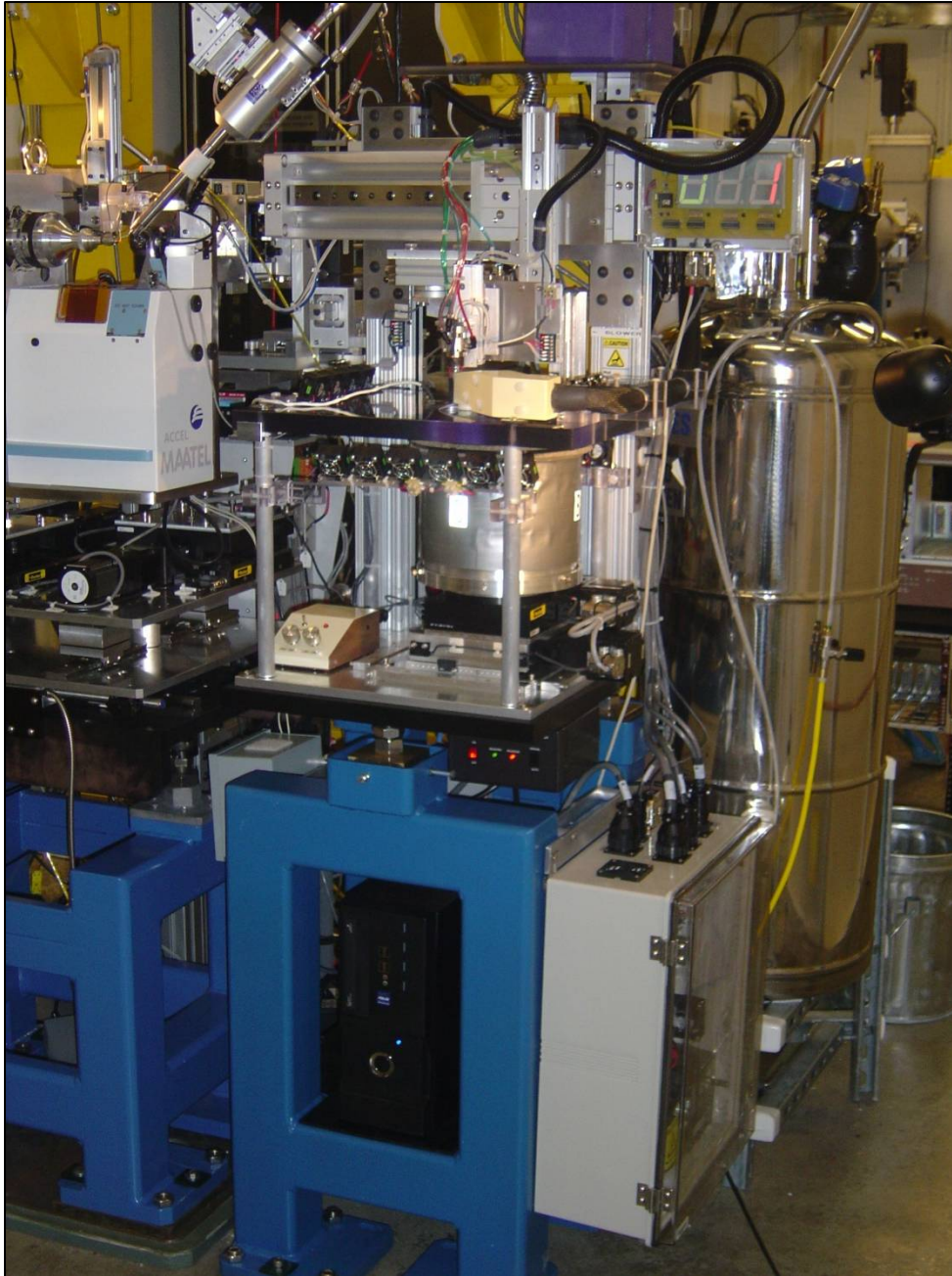


# Refinements to the ALS Crystallography Sample Loader

Malcolm Capel  
Cornell University  
NE-CAT



### **Simplicity:**

- 2 stepper axes
- 6 pneumatic axes
- PLC controls

### **Low Cost:**

- \$25K capital components
- Sweat Equity

### **Safety:**

- Can't collide with detector or users

### **Downside:**

- No intelligence / adaptability

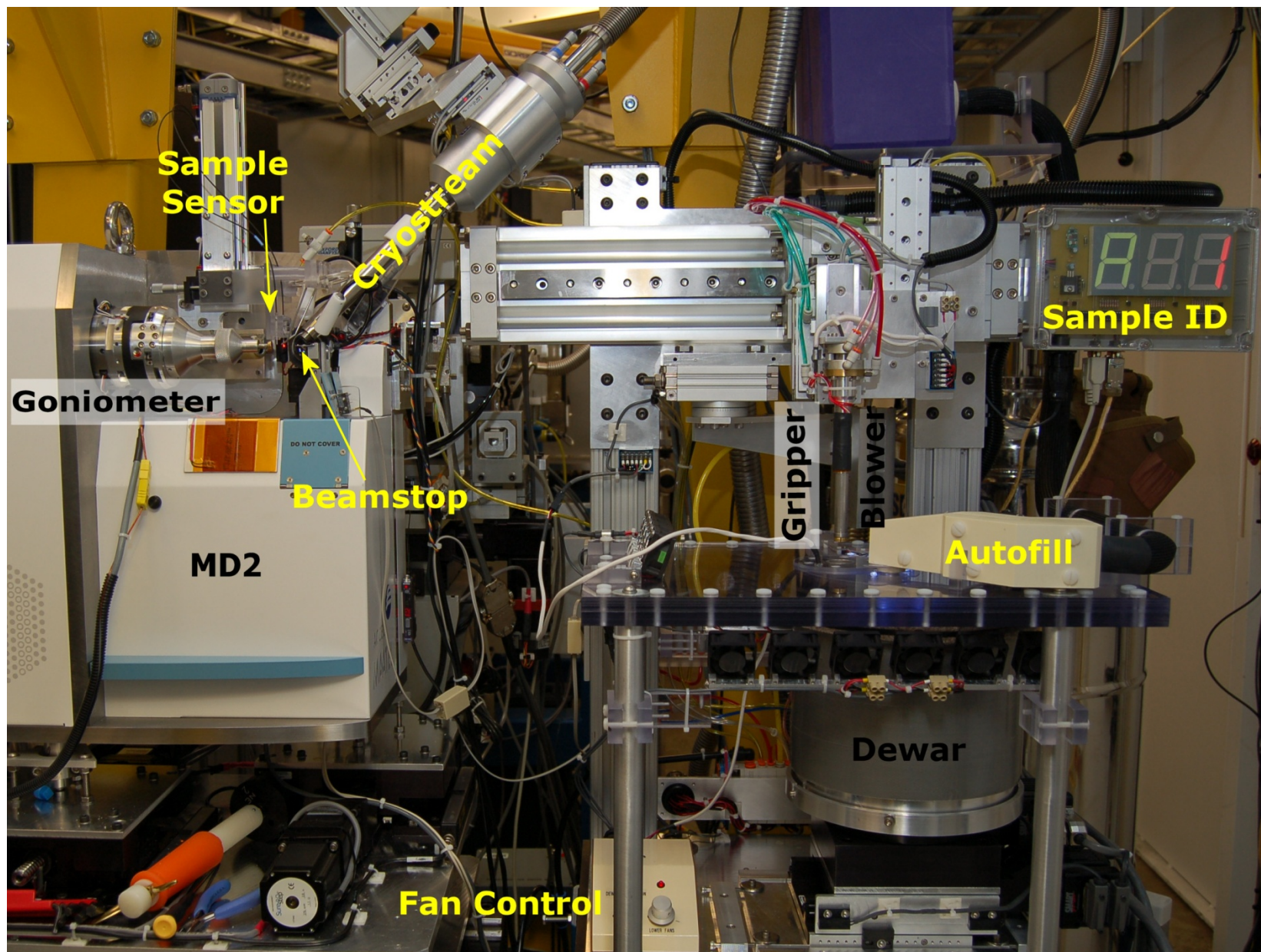
- Limited sample format compatibility

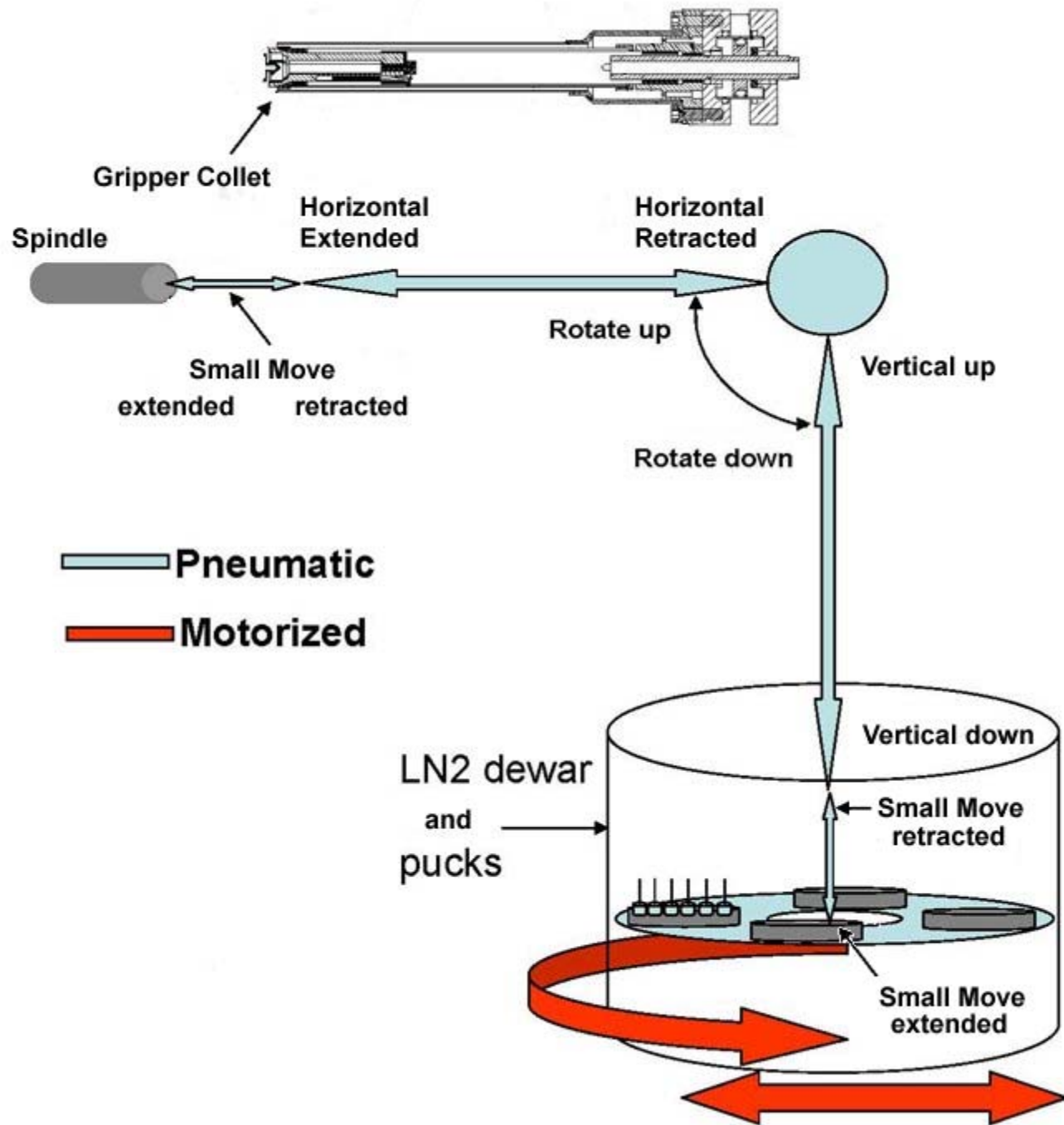
- Relatively low sample capacity (64 in our implementation)

- Can't mount from vials (forces sample transfer operation).



# Relation to MD2 Microdiffractometer



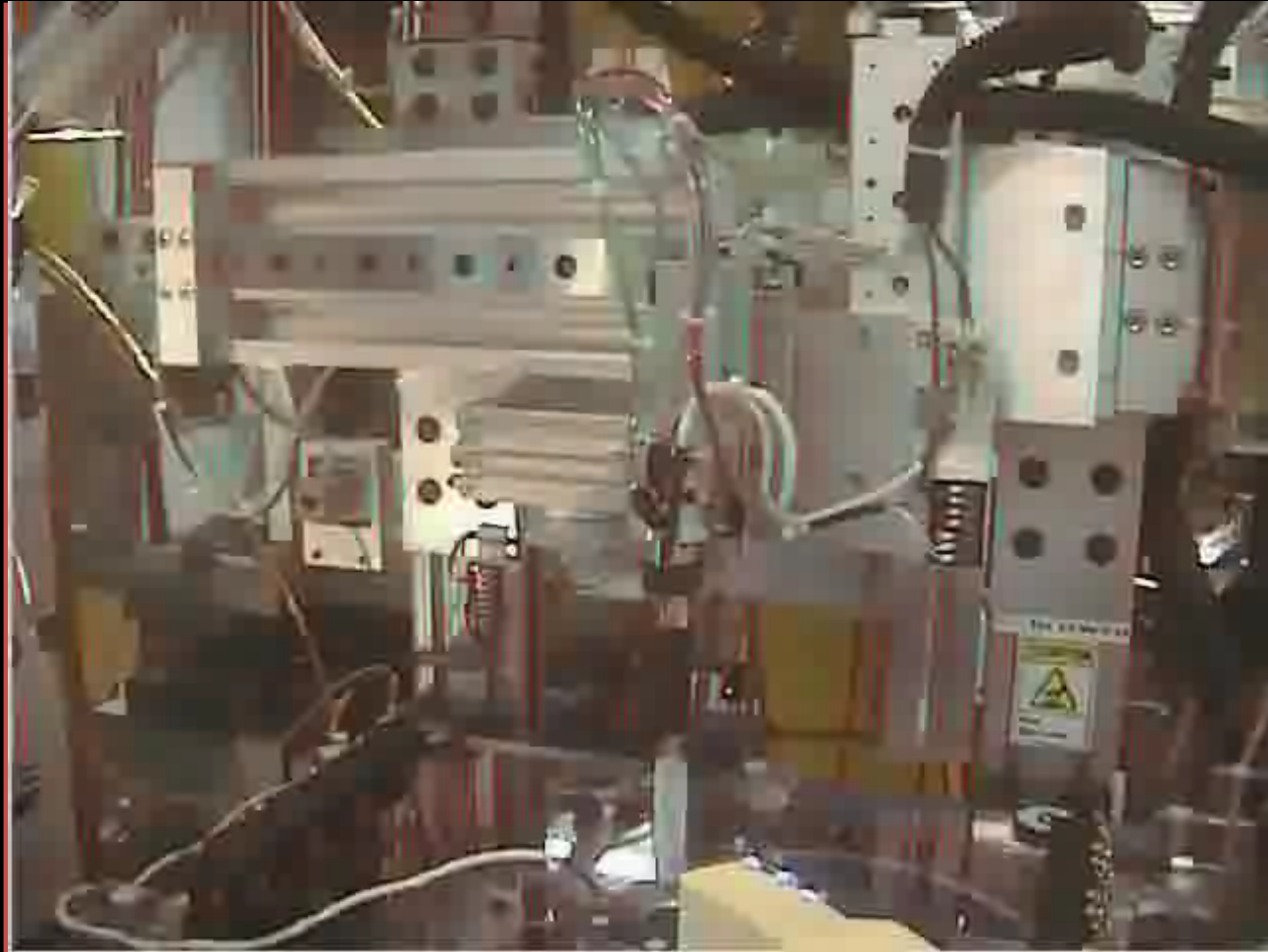


# Stepper-Driven Stages





# Pneumatic Stages





## Compatible Sample Mount Formats

**YES**



CrystalCap  
ALS



CrystalCap  
HT

**NO**



MAR  
Spine



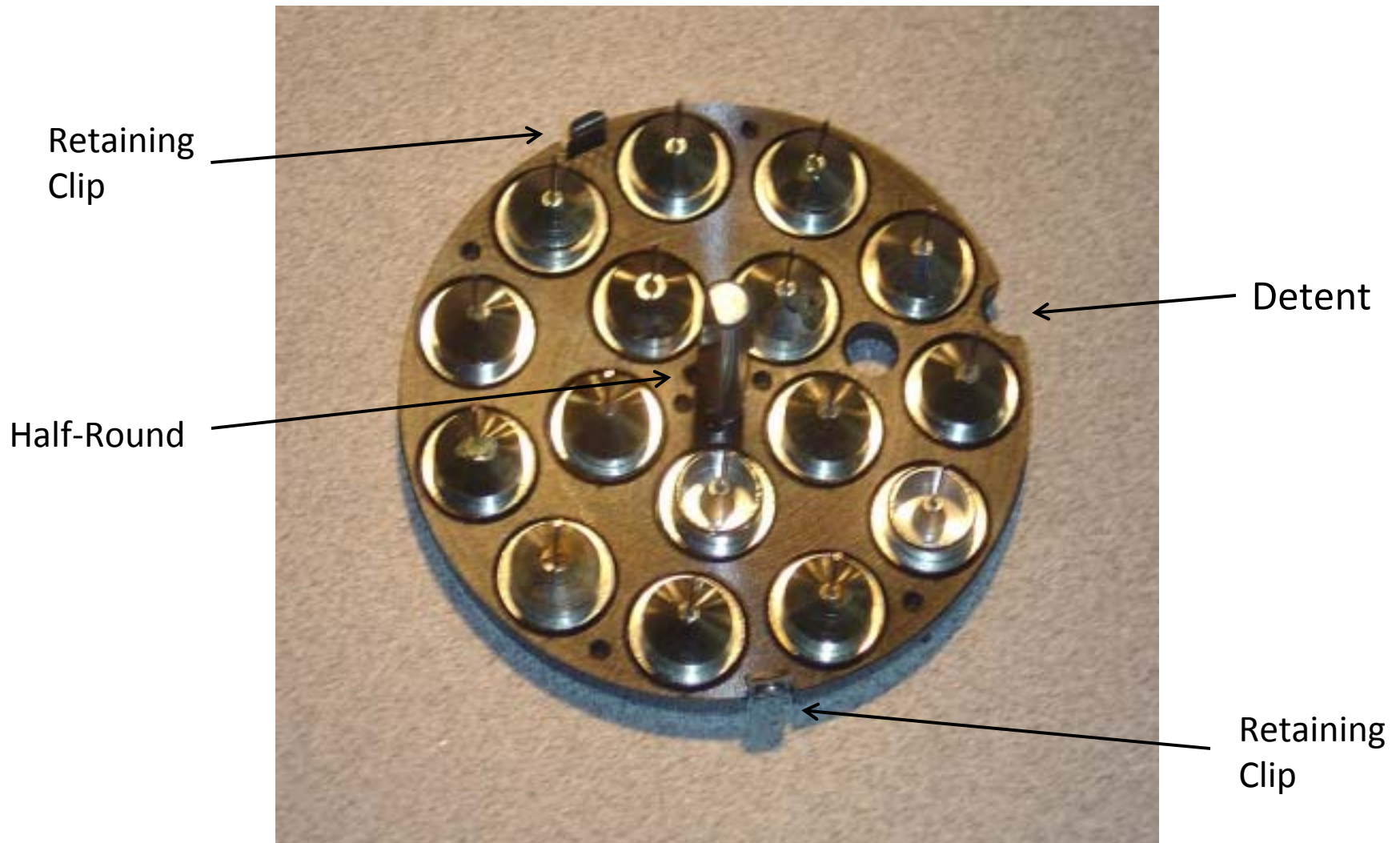
Original  
CrystalCap

# Sample Carriers (Pucks)

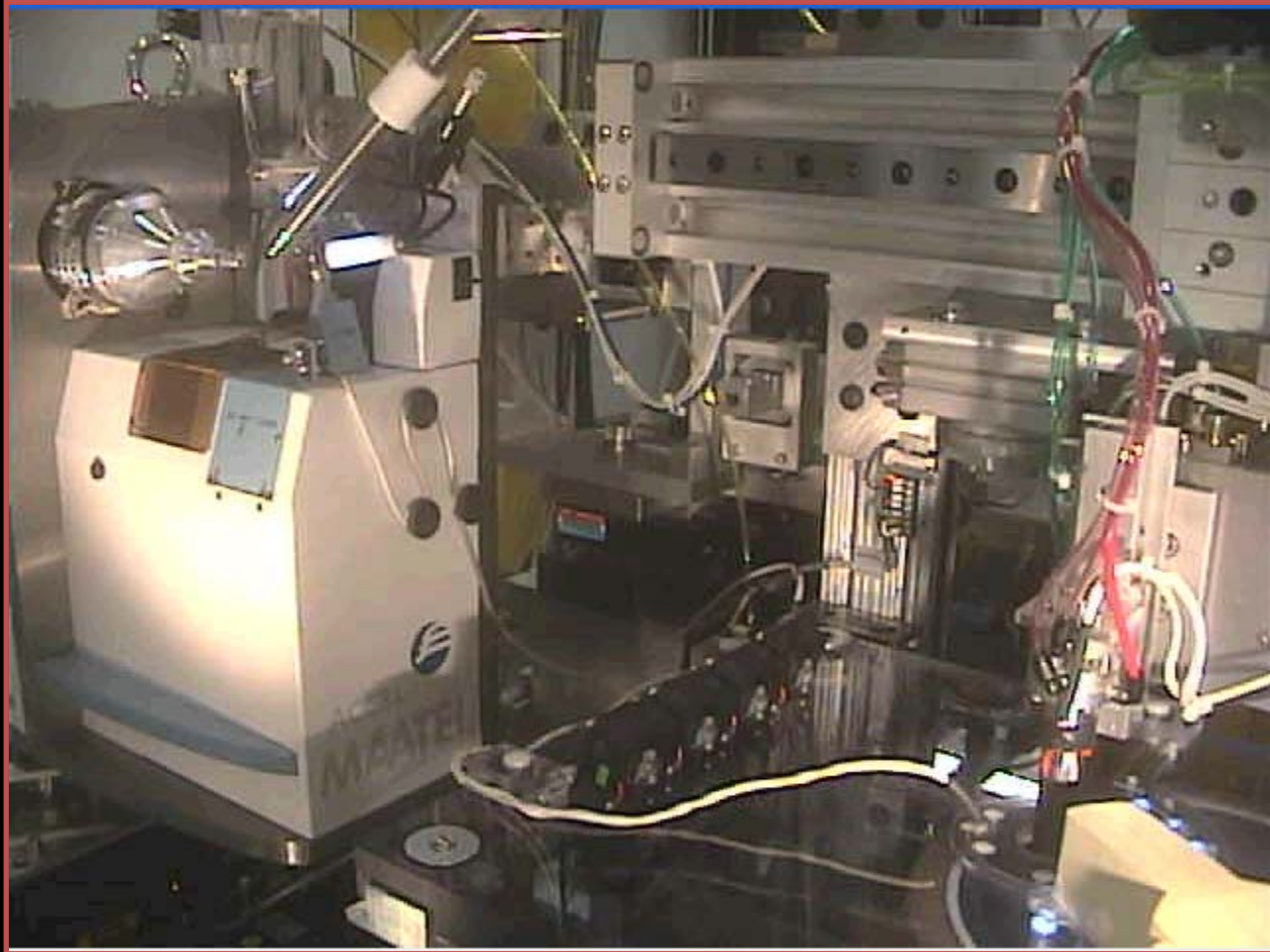




# Puck Lid



# Sample Mount





# Tabulation of Refinements

Overall redesign of the ALS robot for ease of maintenance, reliability and compatibility with NE-CAT's sample goniometry (Maatel MD2).

Puck mounting plate and dewar lid redesigned to enable visualization of dewar interior & improve ease of puck installation and recovery.

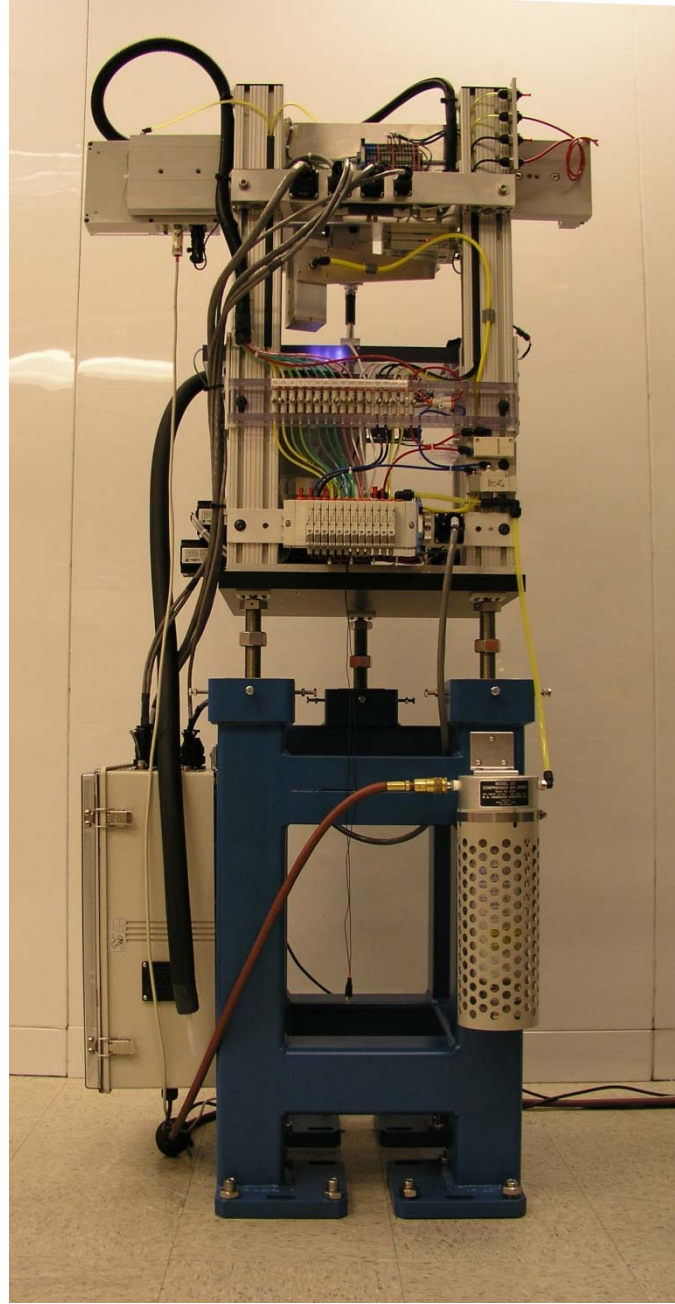
LN2 Distribution revised to increase reliability & minimize turbulence during filling.

Modified gripper mount to minimize mechanical shock to spindle bearing during sample loading and recovery.

Mitigate frost build up on sample gripper, sample dewar and dewar lid.

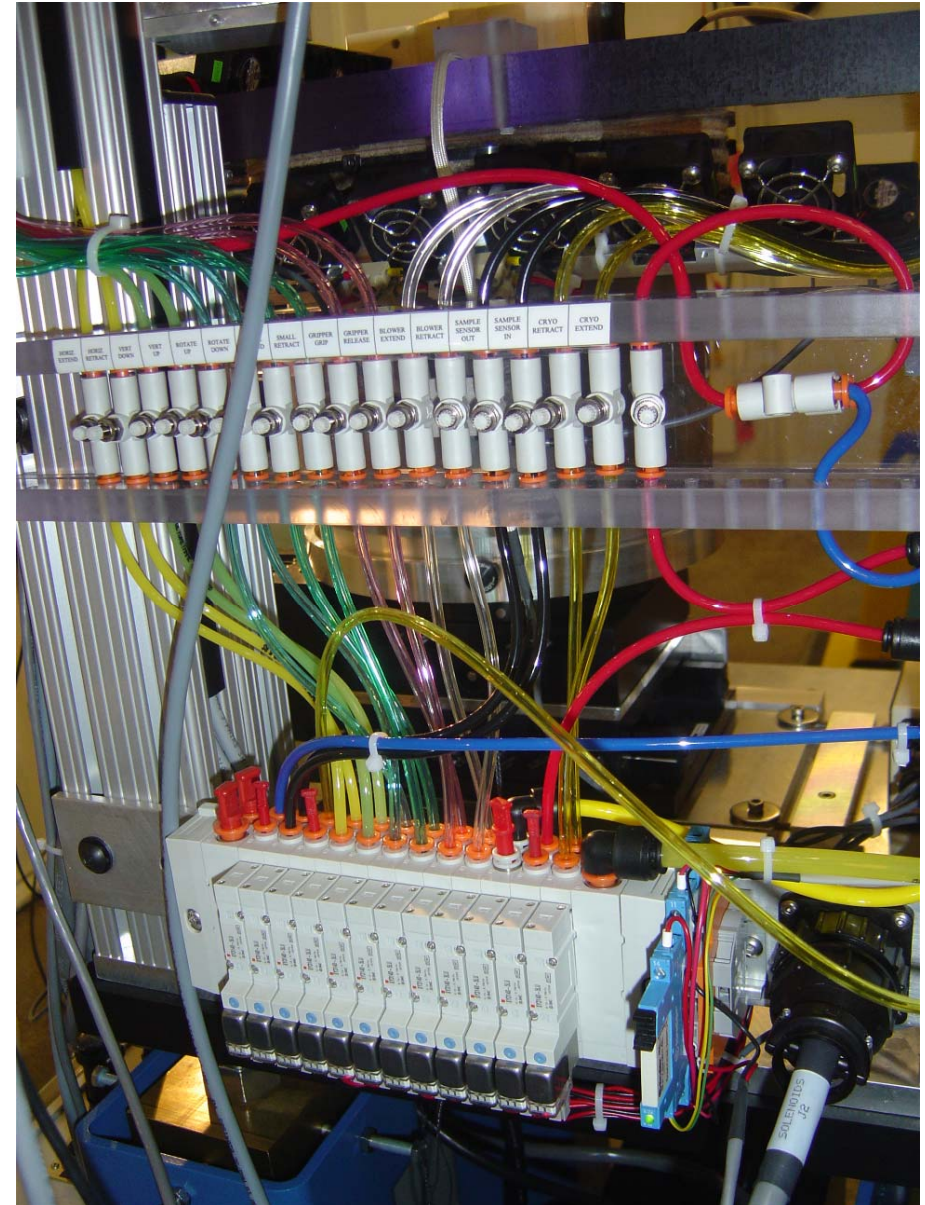
Automatic methods for removing weakly-bound frost from samples

Streamlined sample transfer to pucks.



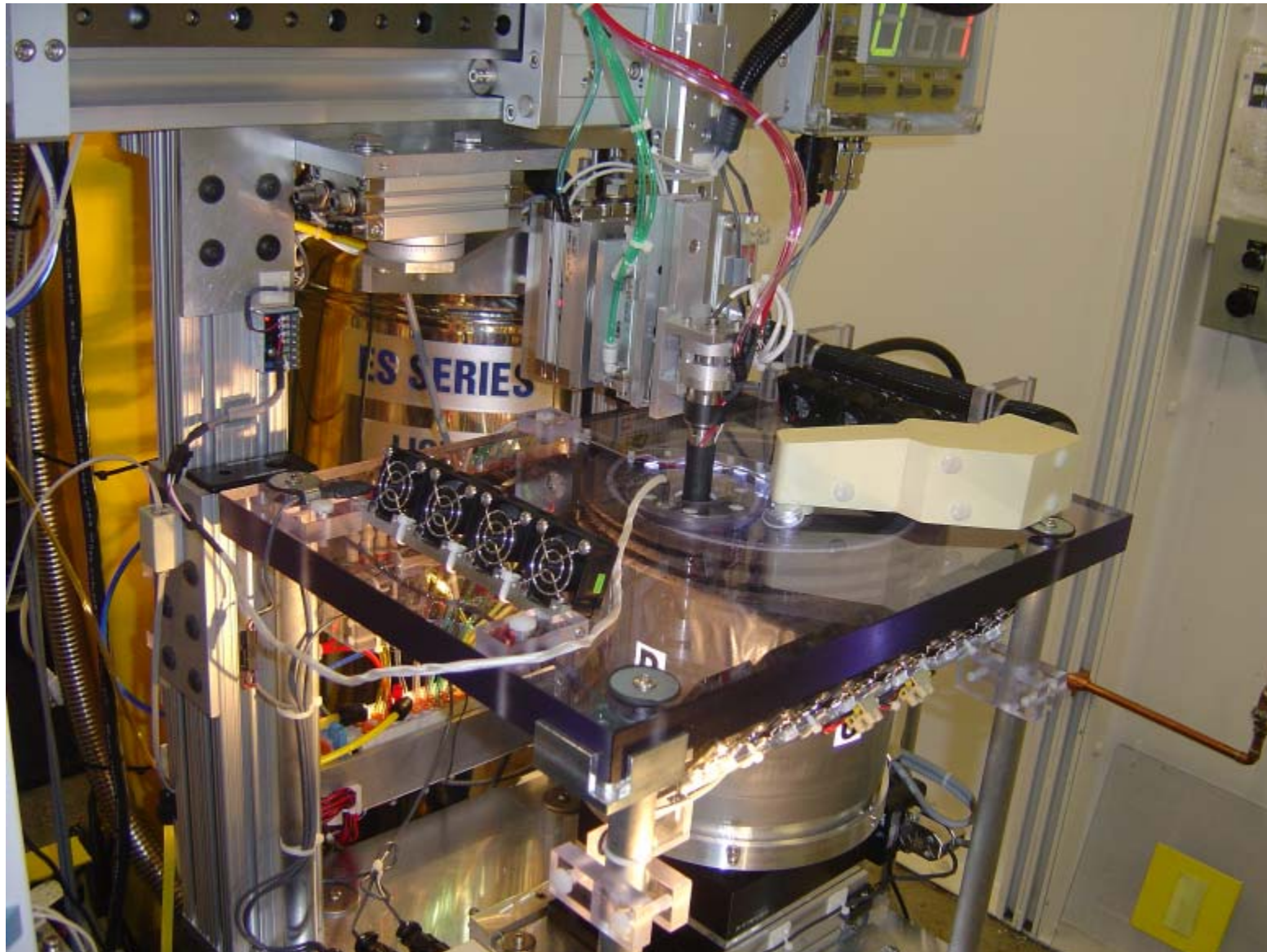


# Re-engineered for Maintainability



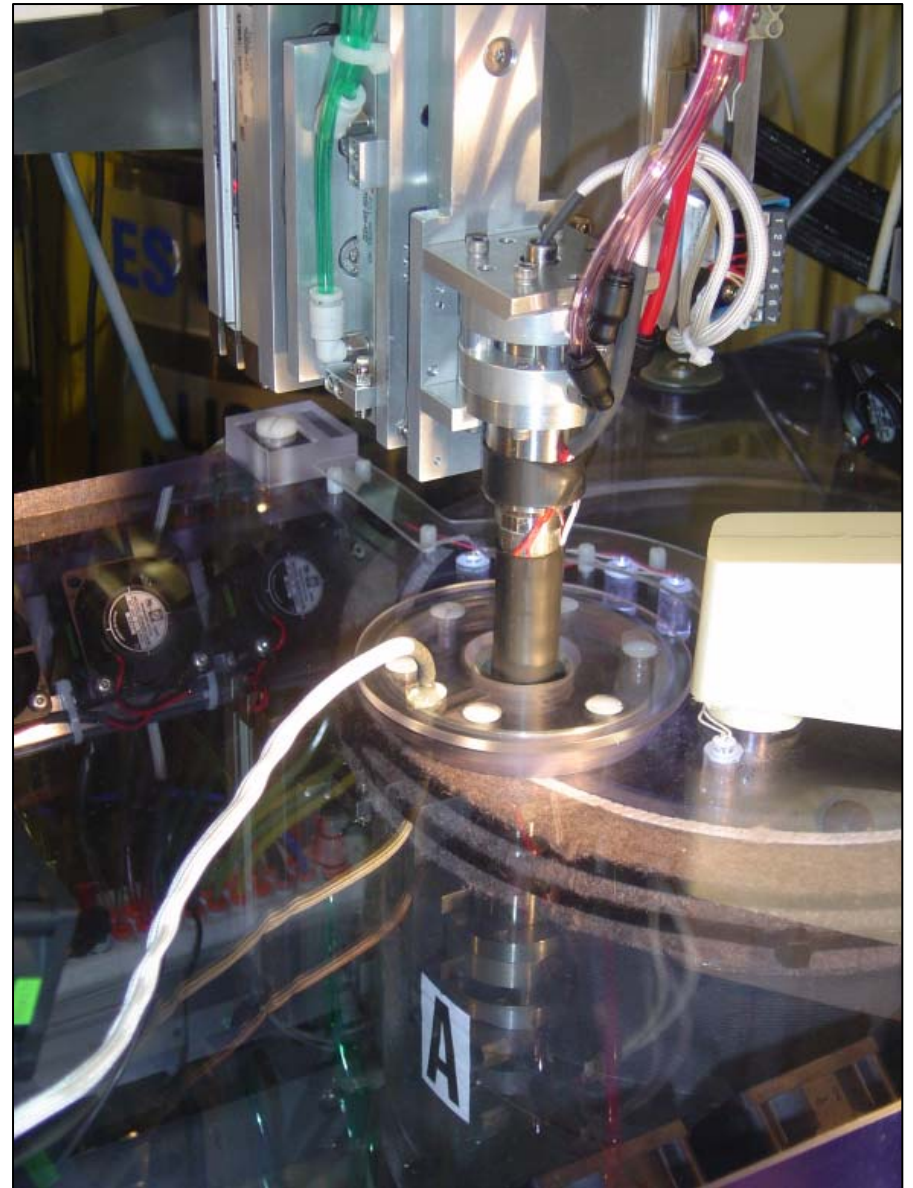
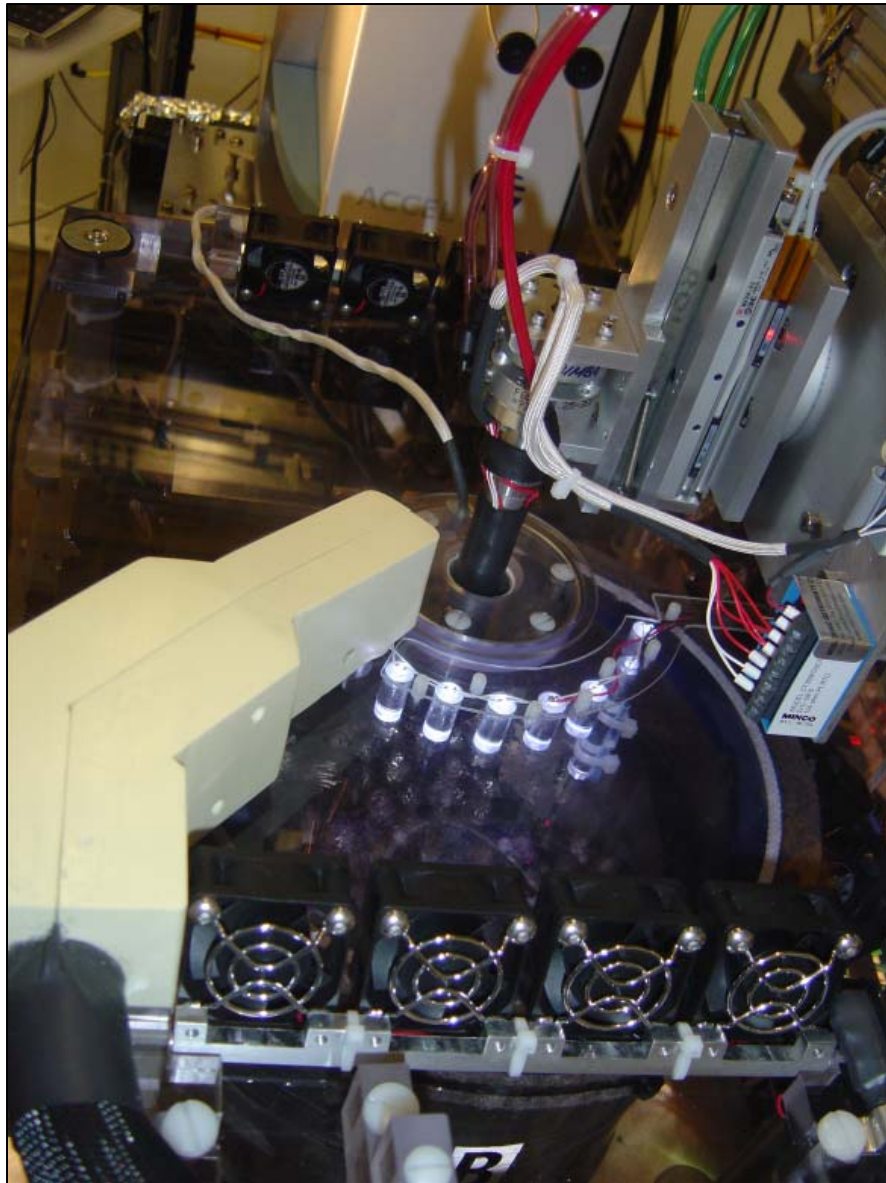


# Transparent Dewar Lid

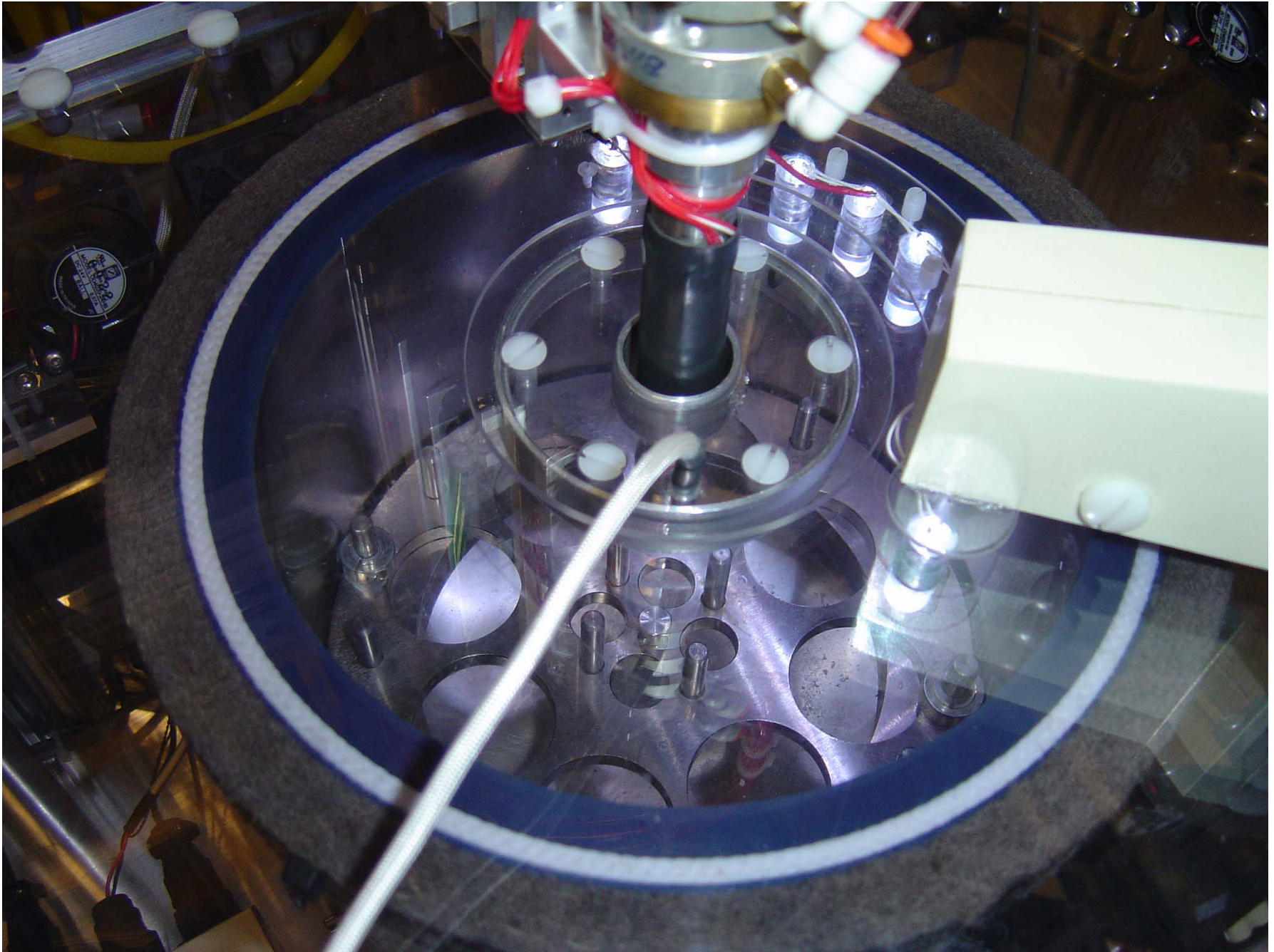




# Illumination LEDs & Anti-Frost Heaters





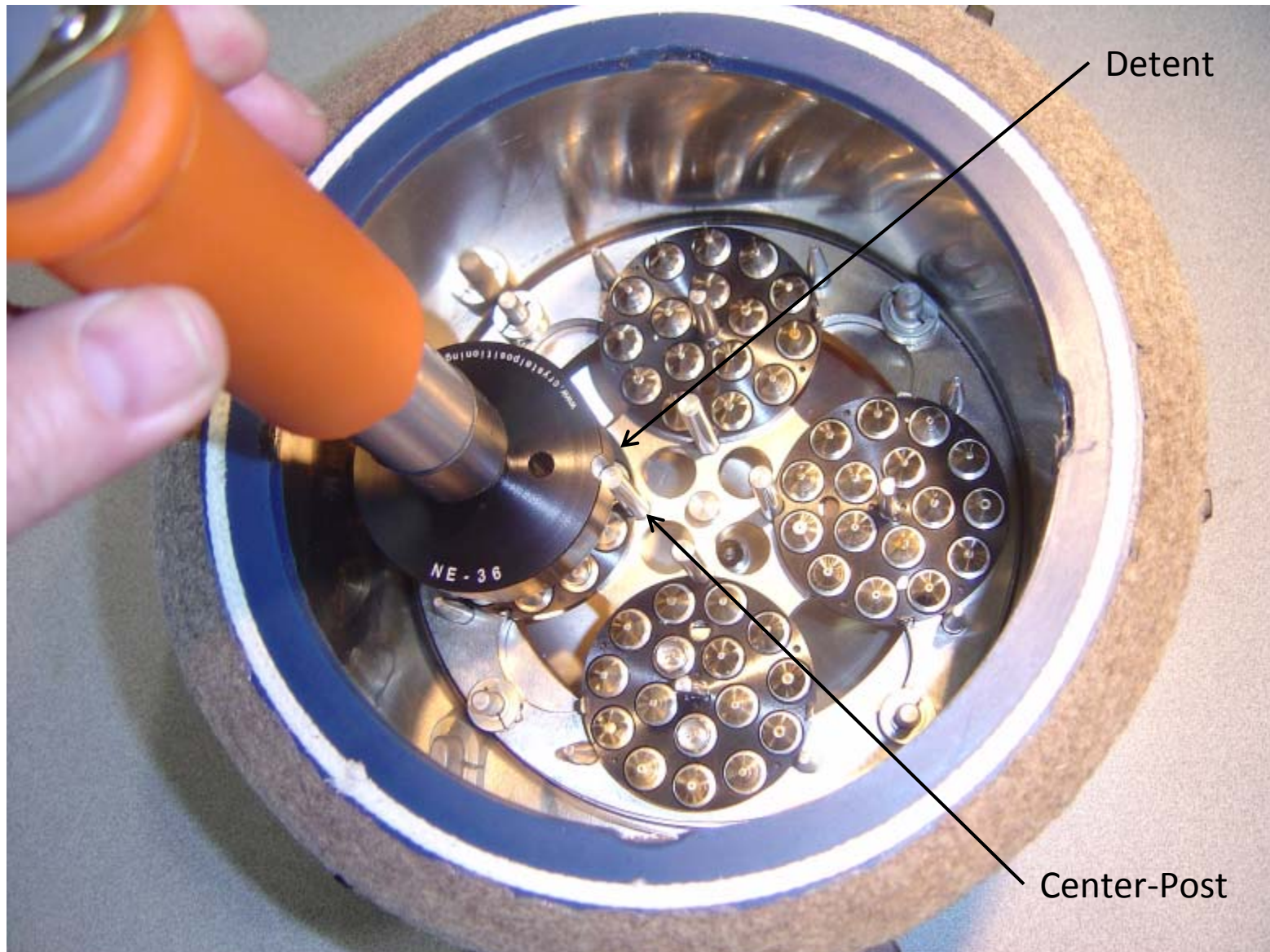




# Dewar and Puck Plate Modifications

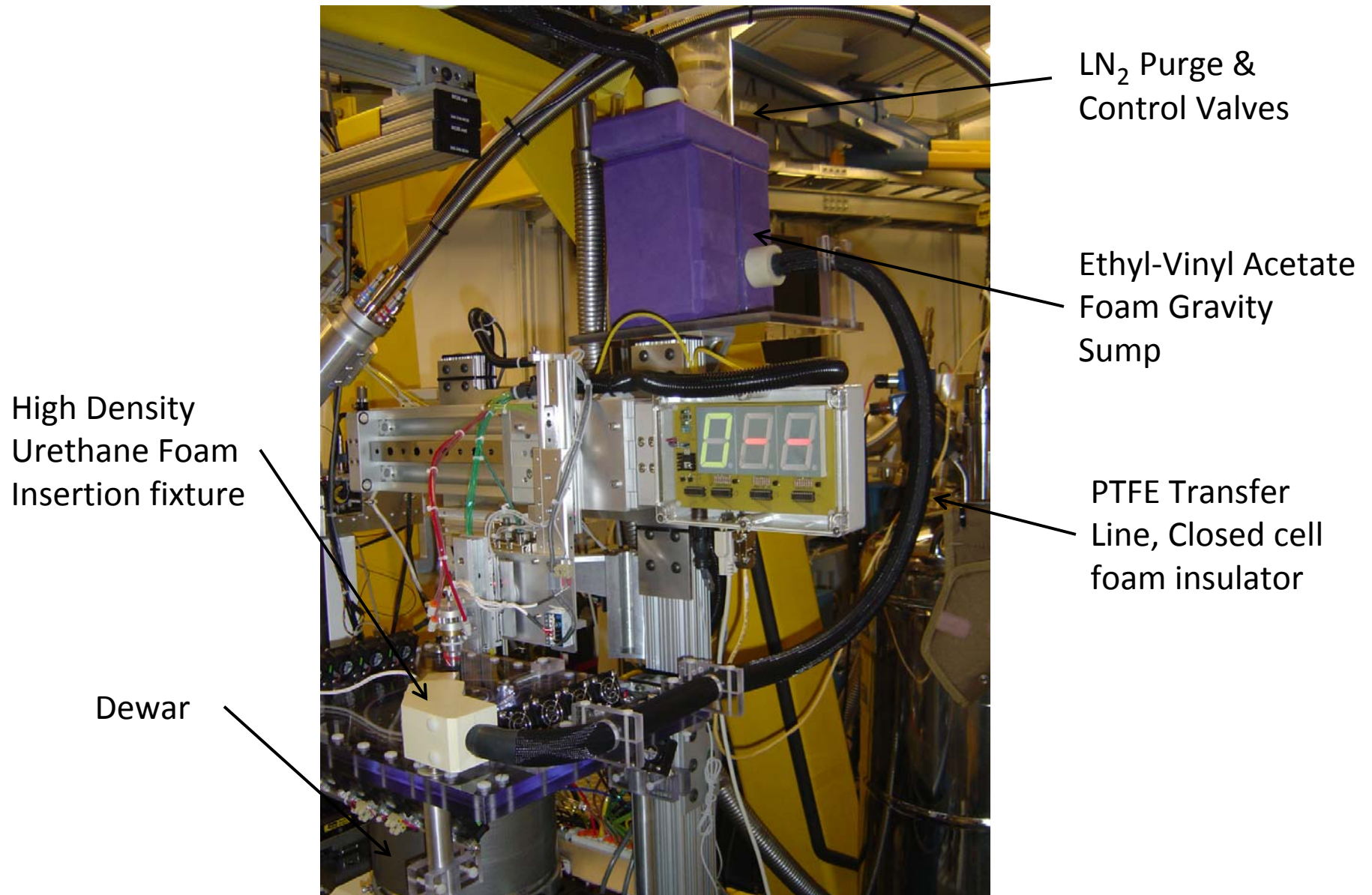


# Center-Post Engagement Prior to Puck Installation or Recovery

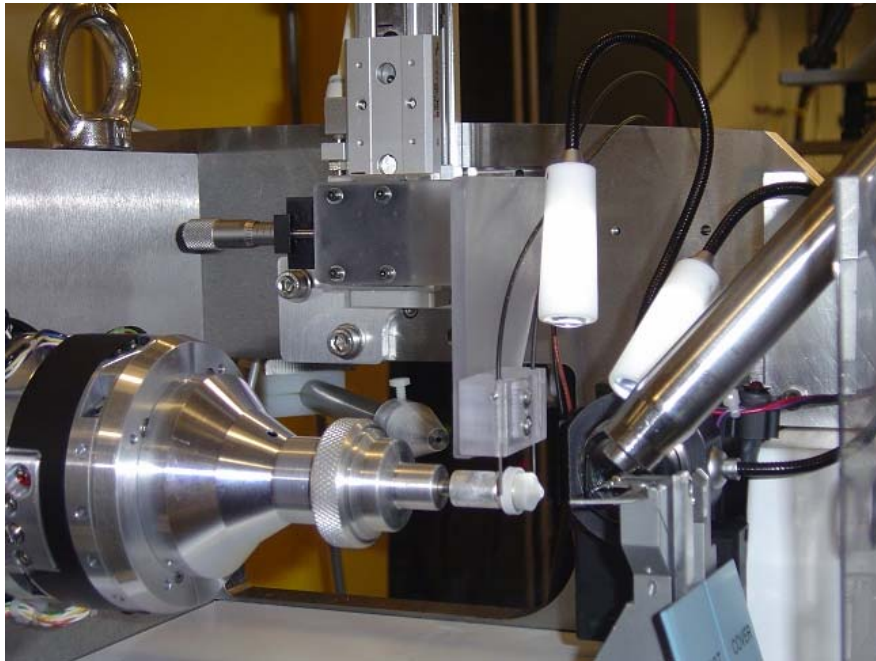
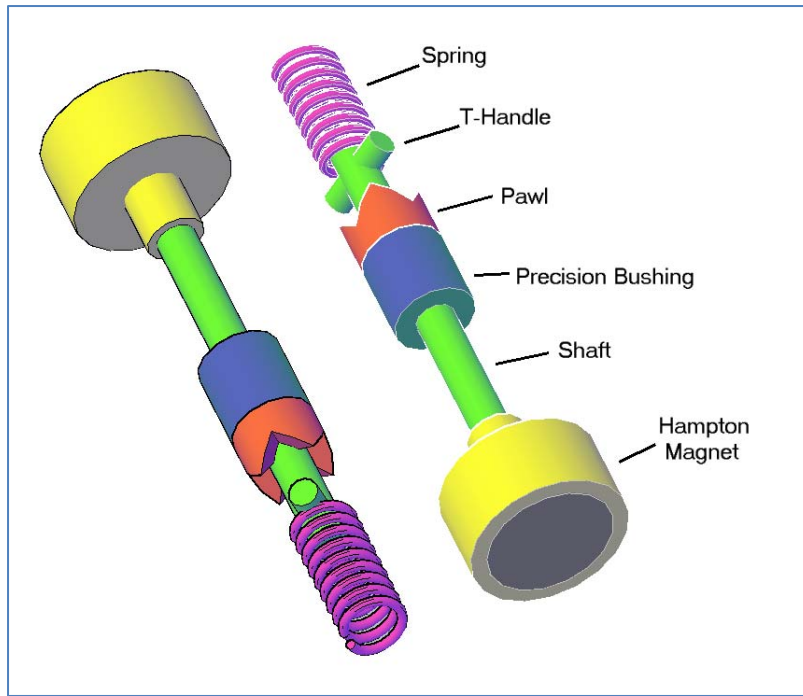




# LN<sub>2</sub> Distribution



# Compliance Head

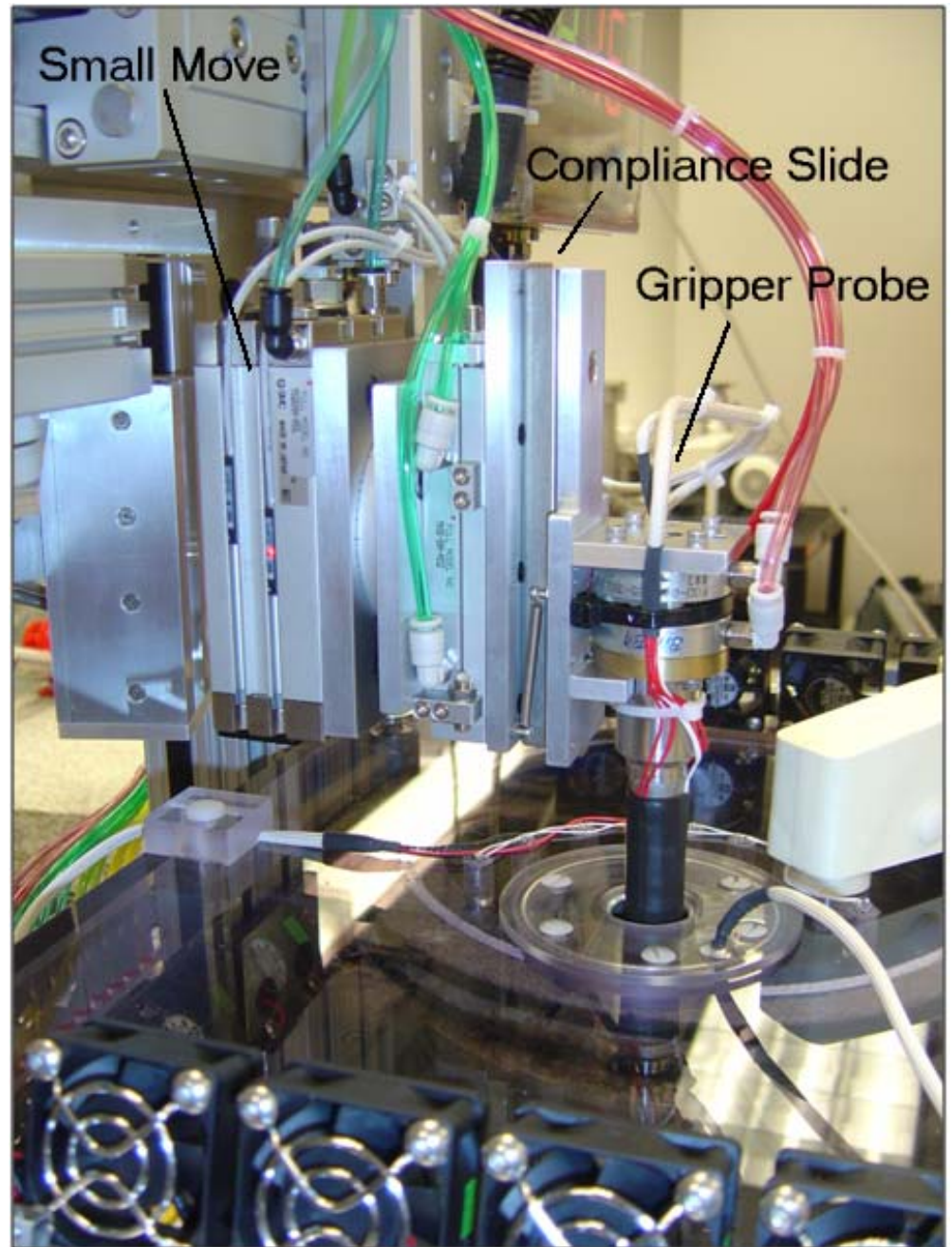




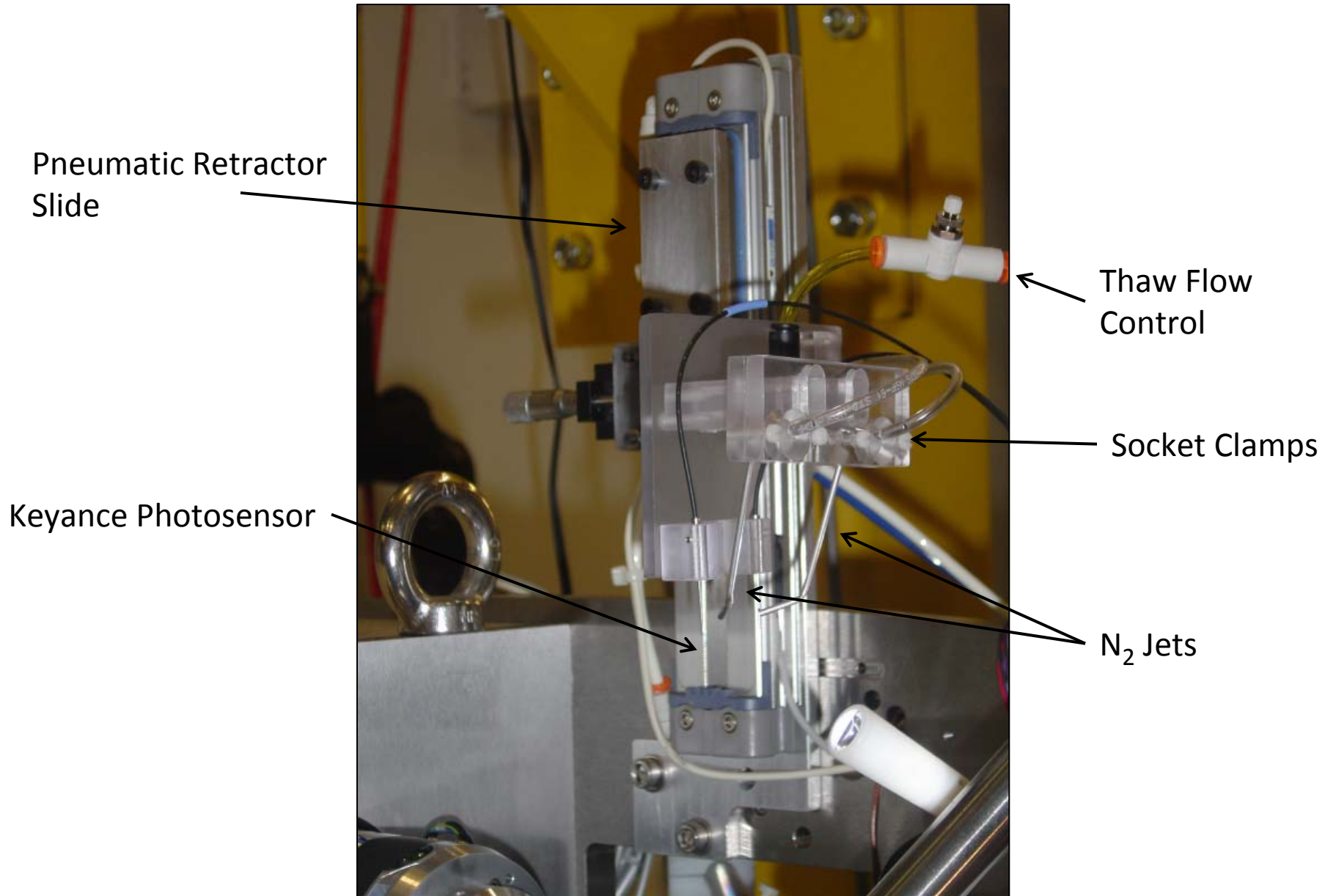
# Compliance Slide



MK3 Mini-Kappa Head



# Sample Sensor & Base Thaw

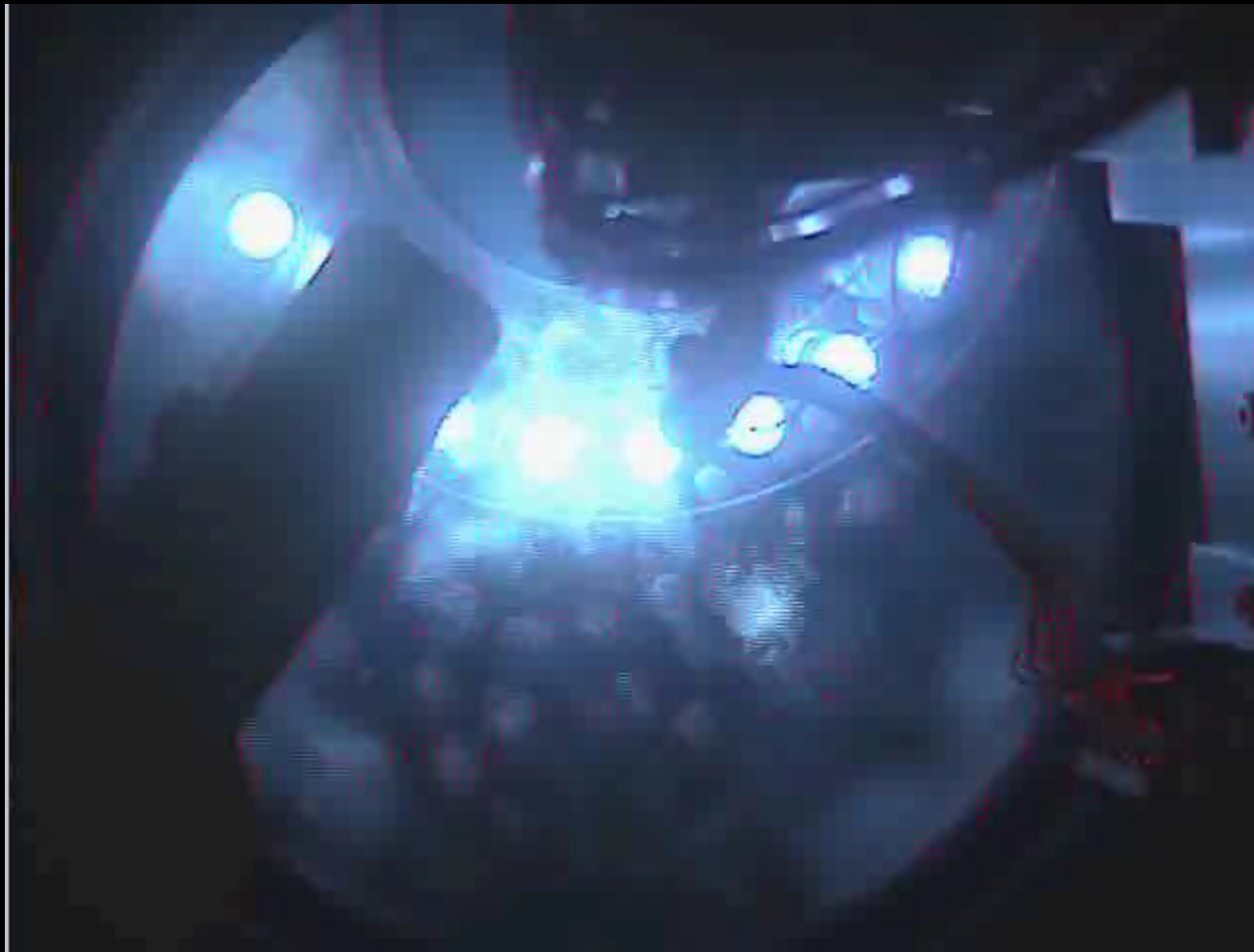




# Sample Mount & Base Thaw

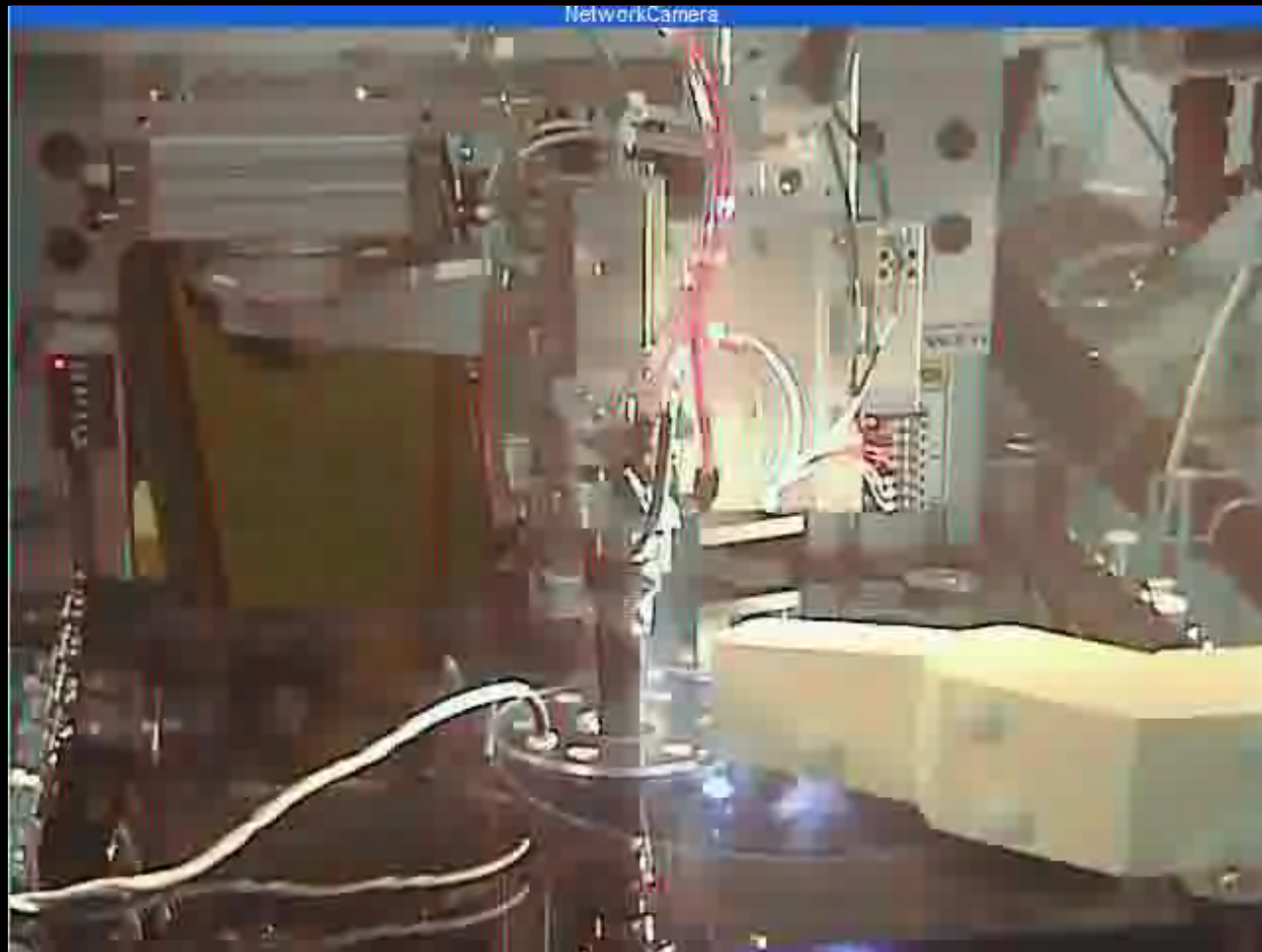


# “Washing Machine De-Icing Mode”





# Agitation De-Icing Mode

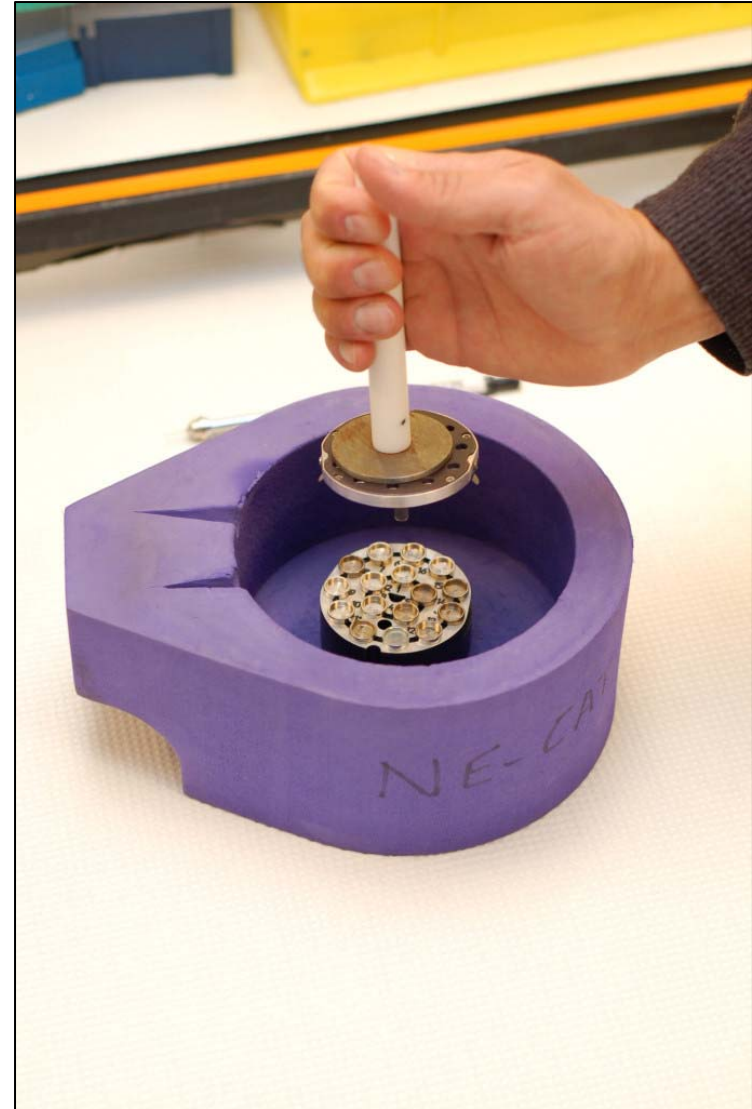
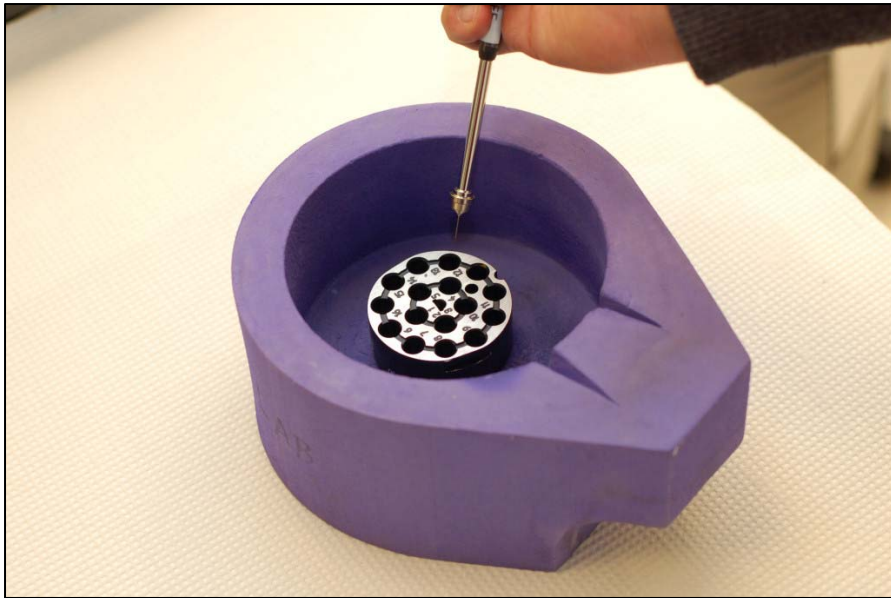


# LN<sub>2</sub> Removal

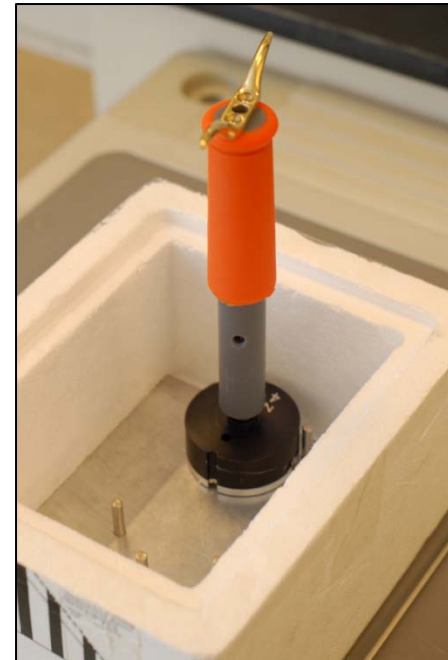
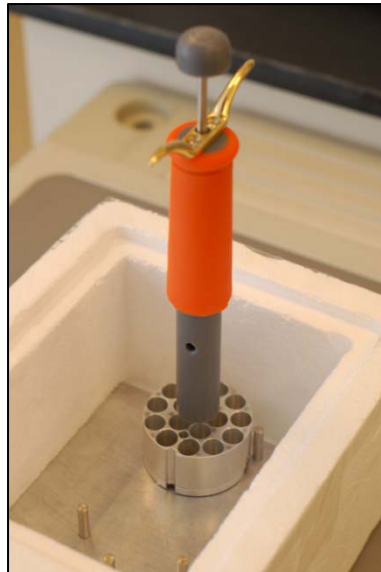
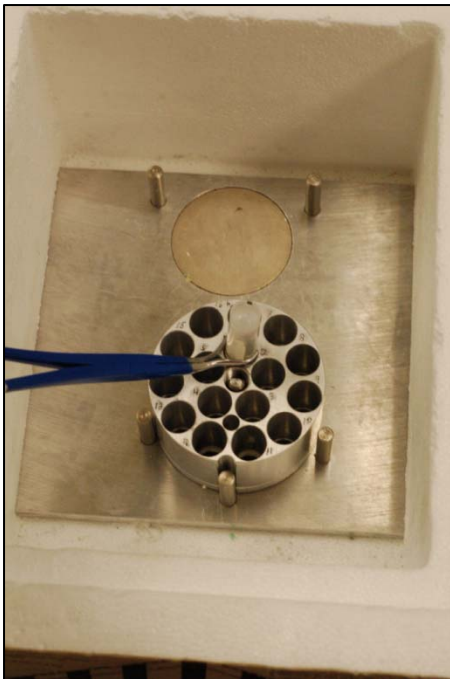




# Old-Style Puck Loading



# SER-CAT's Puck Loading Method





# ALS-Style Puck Availability

Peter Boyd (Boyd Technologies) deceased 2009.

New Source: Richard Howells  
Crystal Positioning Systems  
29 Stafford Street  
Jamestown, NY 14701  
Telno: 716 483-3276  
Faxno:716-483-0018

<http://www.crystalpositioningsystems.com/Puck.htm>