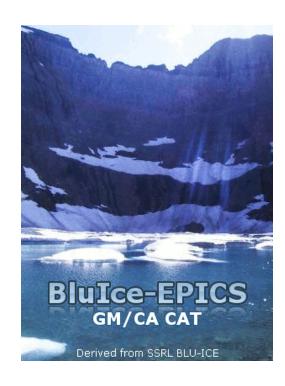


Transition of GM/CA-CAT data acquisition software from Blulce to JBlulce

Mark Hilgart

GM/CA CAT at the Advanced Photon Source Biosciences Division of Argonne National Laboratory USA

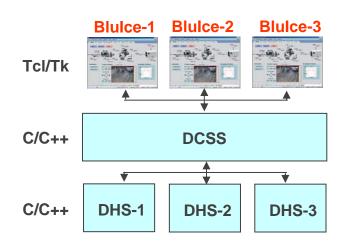


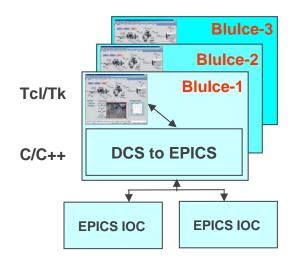
Control Software Requirements

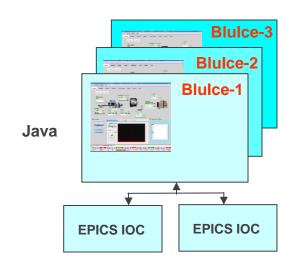
- GM/CA is a macromolecular crystallography beamline
- Our users require:
 - Familiar interface
 - Crystallographers are highly mobile
 - Need to use software at different beamlines with little training
 - Rapid, reliable feature development
 - Crystallographers have many choices of beamlines
 - Advances from other beamlines must be incorporated quickly
 - New features must be released quickly before others do yet must be high quality



History of JBlulce







Blulce Architecture (SSRL)

Blulce-EPICS Architecture

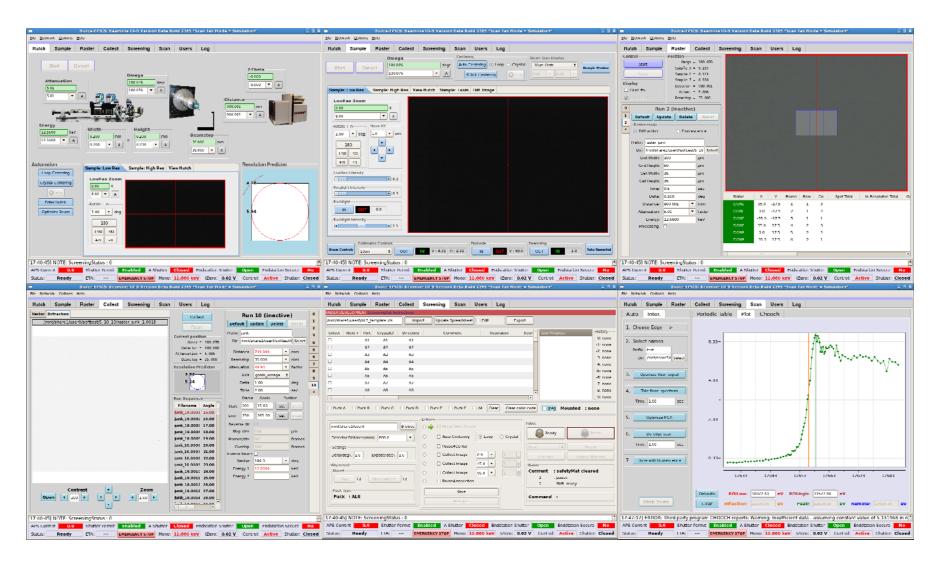
JBlulce architecture

SSRL Blulce: 1997

GM/CA replaced SSRL Blulce backend: 2003-2005

GM/CA developed JBluIce: 2008-2010

JBlulce-EPICS: 100% Java in June 2010



What changed from Blulce to JBlulce?

- Multiple languages -> single language
- C++ -> Java
- Architecture changes
- Features



Single language: Advantages

- Easier debugging
 - Full stack trace is always available
 - Step-through debugging always works
- Higher reliability
 - Thanks to easier debugging and JVM protection from memory errors
- Faster development
 - No protocol layer means changes are much easier



What changed from Blulce to JBlulce?

- Multiple languages -> single language
- C++ -> Java
- Architecture changes
- Features



Java: JVM prevents memory errors

- Java removes uncertainty about memory corruption
 - Tools like valgrind and electric fence, and classes like checked pointers, are not required
- Tracking down the sources of crashes was a major issue in 2007-2008



What changed from Blulce to JBlulce?

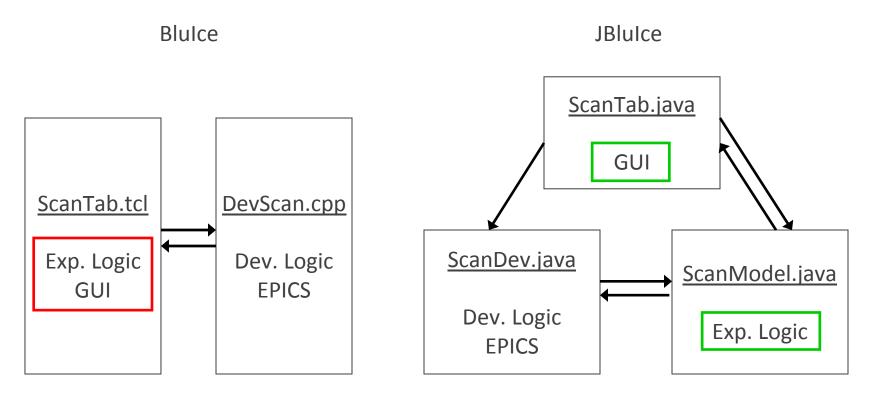
- Multiple languages -> single language
- C++ -> Java
- Architecture changes
- Features



Architecture: Thread-based actions

- Blulce-EPICS had some threaded commands, but now all are converted
- Single 1-2 page methods tell the whole story of an action
 - In a thread, the line number tells you a lot about what's happening
 - In a callback-based class, which timers are running, and which callback will be called next?
- Perl scripts are written this way, so porting methods (and keeping in sync) is straightforward

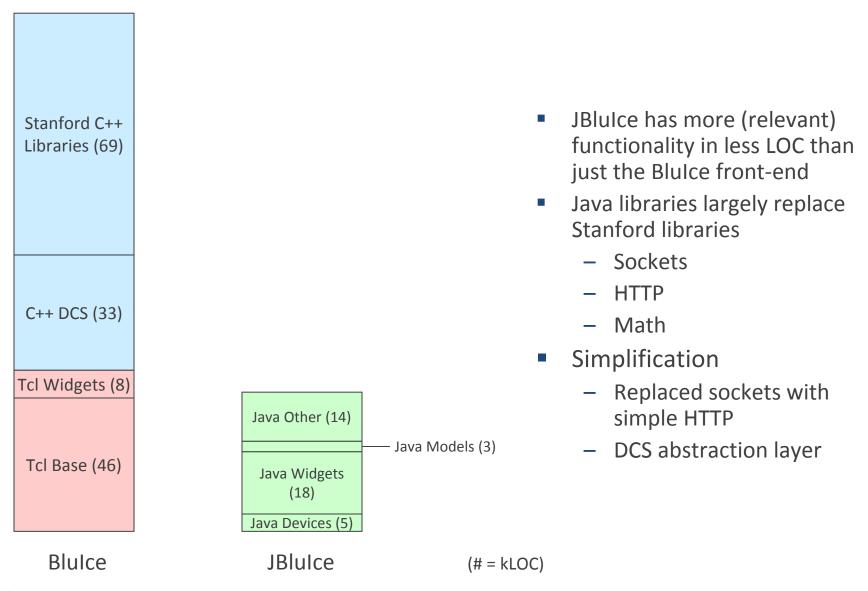
Architecture: Separation of logic, GUI & devices



- SSRL BluIce mixes logic in GUI widgets
- JBluIce usually makes <u>one-line calls to model objects</u>
- Only devices talk to EPICS (except for temporary calls)



Architecture: 3x LOC reduction

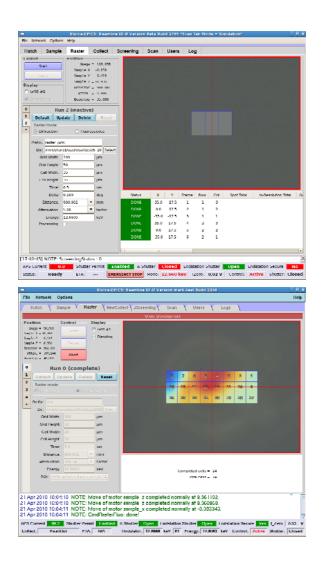


What changed from Blulce to JBlulce?

- Multiple languages -> single language
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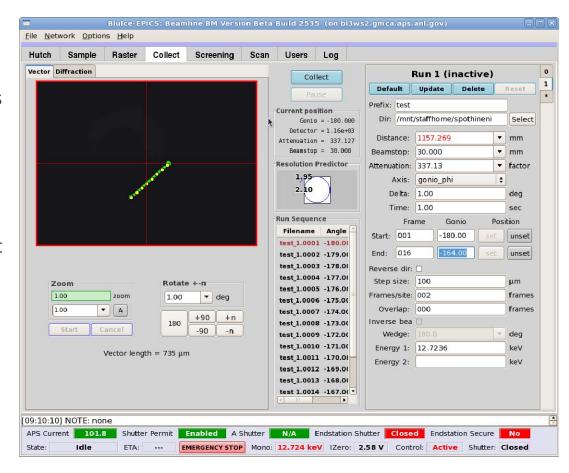
Features: Raster



- 2008-2: Initial release
- 2009-2: Fl. raster
- 2010-1: Multiple run tabs
- Two uses
 - Find invisible crystals
 - Find the best diffracting areas of large crystals
- Diffraction vs.
 fluorescence
 - Diffraction is always relevant
 - Fluorescence is 4x faster and causes less radiation damage

Features: Vector collect

- Data collection along an arbitrary 3D vector
 - To define, center endpoints and click "set"
- Uses
 - Collect along rod-shaped crystals
 - Raster crystals that don't fit the rigid raster tab grid
- Visualization over live video
- Parameters for:
 - Frames per site
 - Site spacing
 - Overlap



Features: Integrated motion tracking

Tracking output

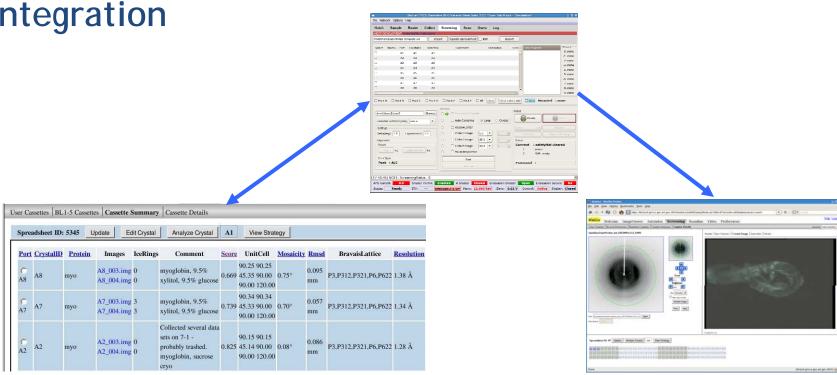
```
[14.530] estimateMoveTime(): motionTime=2.1s accelTime=200.00s accelCurve=100.00s ...
[14.531] elap.=
                0.0s inPos=1 runPrg=0 actPos=-0.0000 ...
[14.633] elap.=
                      inPos=1 runPrg=0 actPos=0.0281 ...
                0.1s
[15.959] elap.=
                1.4s
                      inPos=0 runPrg=1 actPos=87.2386 ...
                1.5s inPos=0 runPrg=1 actPos=89.9528 ...
[16.061] elap.=
[16.163] elap.=
                1.6s inPos=0 runPrq=0 actPos=89.9997 ...
[16.265] elap.= 1.7s inPos=1 runPrq=0 actPos=89.9998 ...
[16.367] elap.= 1.8s inPos=1 runPrg=0 actPos=89.9998 ...
[16.469] elap.= 1.9s | inPos=1 runPrg=0 actPos=89.9998 ...
[16.478] Tracking ended. Real in-motion time for motor gonio omega was 1.9s (92.3% of est.)
[16.478] Motor gonio omega, no errors detected.
```

- Tracking guarantees motors are in position, and handles errors and timeouts
- In Tcl/C++, tracking was added in the background
 - DCS protocol didn't support tracking
 - Tracking was done in the background but could be ignored
- In Java, tracking determines when a move finishes
 - Moves always complete, by timeout if necessary
 - Move results are more informative because they incorporate tracking



Features: Editable spreadsheet and Weblce





- New features built in to the initial converted screening tab:
 - Spreadsheet can be edited and saved without using OpenOffice or Excel
 - Screening results are sent automatically to Weblce
- 2010-1: Weblce scores can be loaded back in to Blulce

Features: 5x startup time reduction

Blulce: 16 seconds

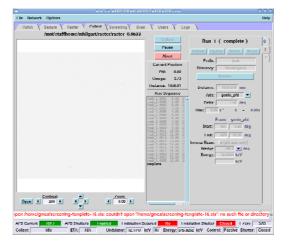
JBluIce: 2.8 seconds

- Tests were performed on the same computer
- Improvement due mostly to connecting PVs in parallel at startup
 - PV requests are sent at once
 - Callbacks are sent as PVs connect

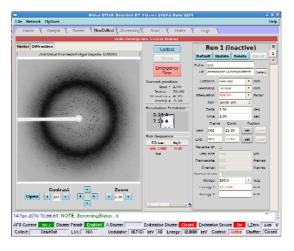


Tcl/Java integration

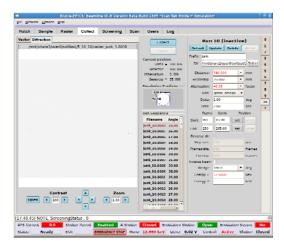
100% Tcl: 2008-1



During conversion



100% Java: 2010-2



- Raster was an initial test
- 1-3 tabs were converted per run
- TkXext embedded Java windows in Tcl
- Named pipes were used for sending commands between processes

Release

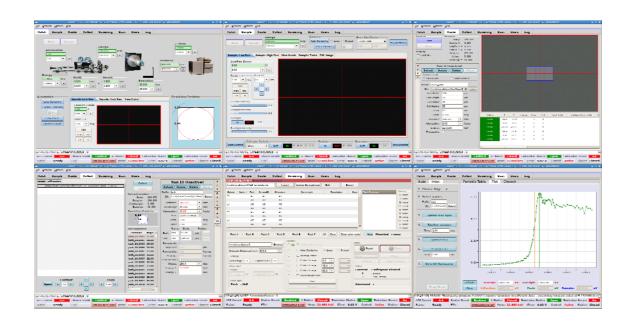
- 2.5 years of development
 - Raster: 2008-2
 - Fl. raster: 2009-2
 - Screening: 2009-3
 - Collect: 2010-1
 - Hutch, Sample, Scan: 2010-2
- Testing
 - Fully functional 4 weeks before users
 - Change cutoff 2 weeks before users
 - Crystallographers tested daily for the last 4 weeks
- Smooth release so far
 - No serious bugs found in 1.5 weeks of users



Conclusion

- Users' demands guide development
 - Familiar interface
 - Throughout development, interface is kept the same
 - Rapid, reliable feature development
 - Architecture has been streamlined to enable fast development and high reliability
- Future plans: concentrate on features





JBIulce-EPICS

JBluice Developers	EPICS Developers	Design Suggestions	<u>Management</u>
		and Testing	
Mark Hilgart	Sergey Stepanov	Craig Ogata	Janet Smith
Sudhir Pothineni	Oleg Makarov	Ruslan Sanishvili	Robert Fischetti
		Michael Becker	
		Nagarajan Venugopalan	
		Derek Yoder	