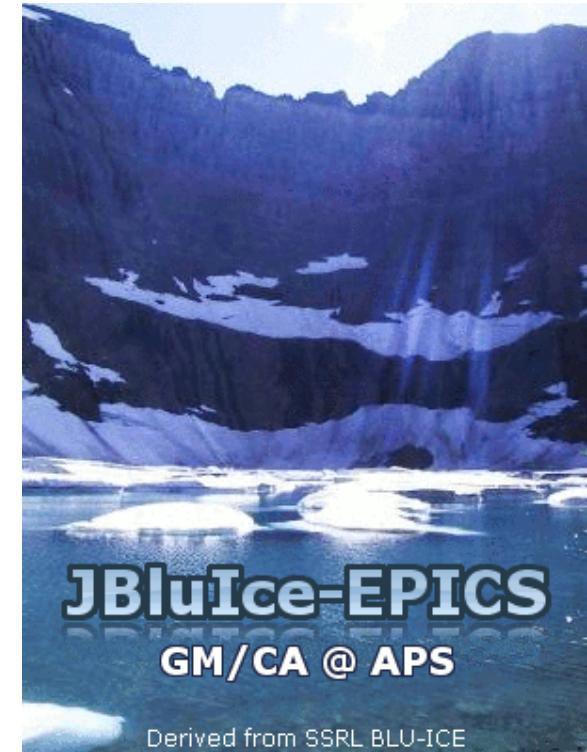


Auto-Raster: Unattended Diffraction-Based Sample Centering at GM/CA

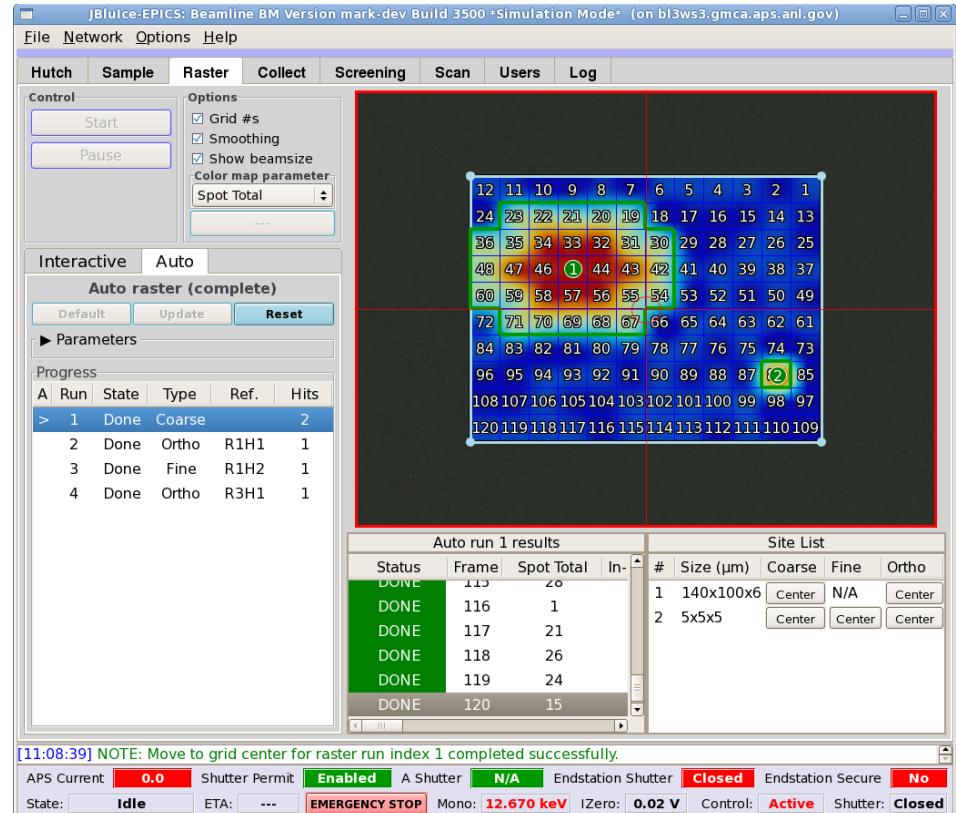
Mark Hilgart, Ruslan Sanishvili, Sudhir Pothineni, Sergey Stepanov, Oleg Makarov, Nagarajan Venugopalan, Michael Becker, Craig Ogata and Robert F. Fischetti

GM/CA@APS



Auto-Raster

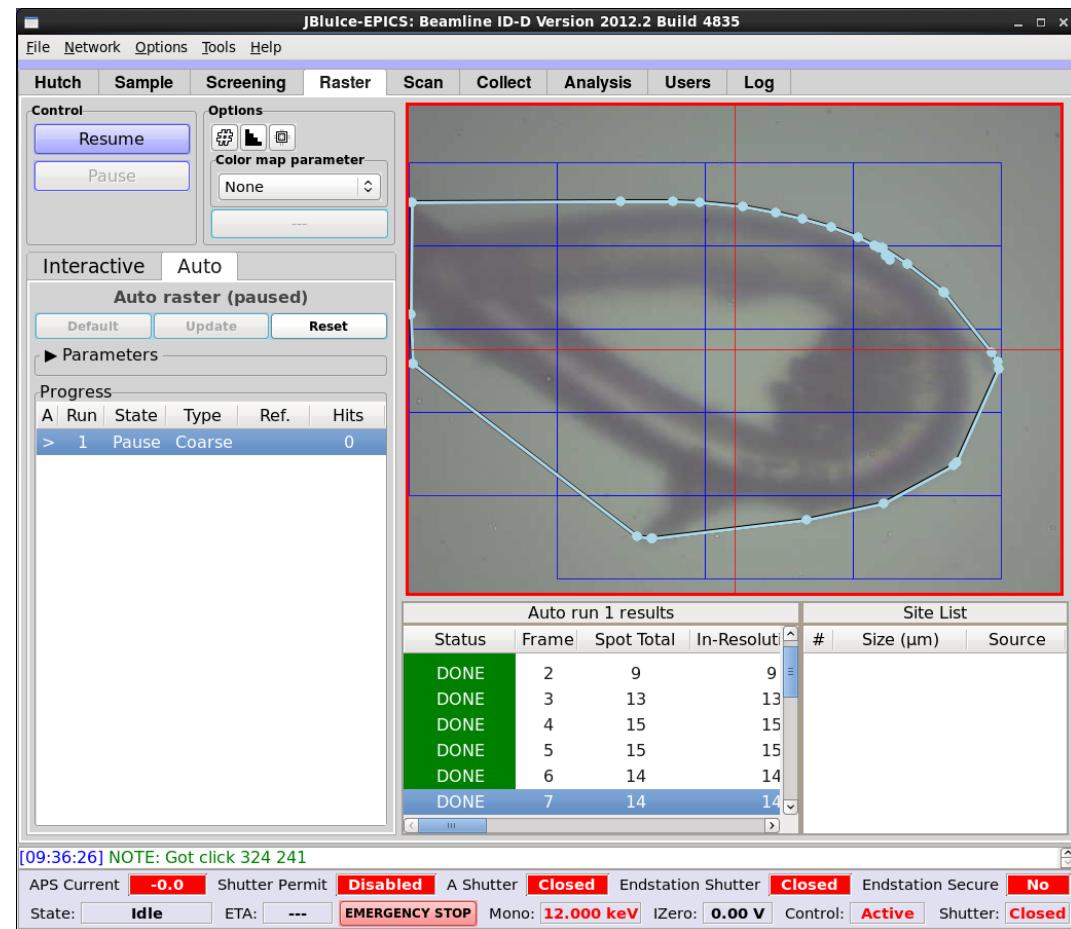
- Auto-Raster is a critical automation step, and also very difficult
 - Many different situations need to be handled
 - If full datasets are to be taken, the centering must be accurate so samples are not wasted
- Process:
 - Sample is **mounted** by a robot
 - Loop is optically **centered**
 - **Grid** is defined to cover the loop
 - **Diffraction** images taken at each cell
 - **Processing** results shown graphically
 - Algorithm sets up successive grid **searches**



Auto-Raster results in JBlulce-EPICS

Algorithm

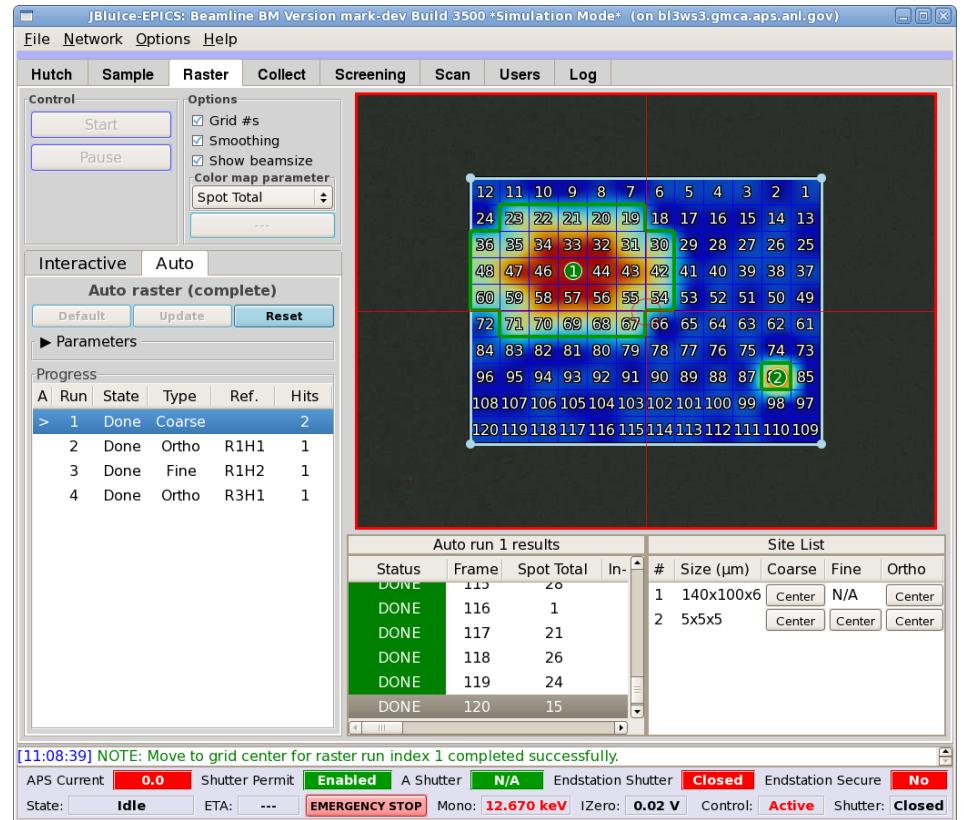
- Stage 1: AutoFind
 - XREC optically centers the loop in face-on orientation
 - XREC returns a polygon outline of the loop
 - Stage 2: Coarse Grid
 - JBlulce fills the XREC-generated polygon with approximately 20 cells
 - An image is taken at each cell and processed with SpotFinder
 - Cells are ranked based on the number of potential Bragg candidates on that image minus a background number
 - Groups of cells are counted as a single “hit”



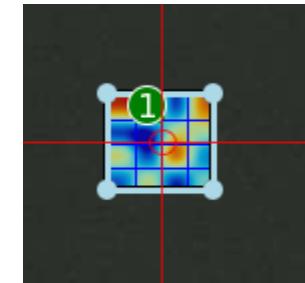
XREC-generated loop outline

Algorithm

- Stage 3: Fine Grid(s)
 - Individual cells from the coarse stage (those with no neighbors) are rastered with a fine beam of 5-20 microns
- Stage 4: Ortho Grid(s)
 - Hits from either the coarse or fine stage are then scanned in the orthogonal plane along a single column of cells
 - Hits from this stage generate 3D “sites” which can be passed to the collect tab
 - Multiple hits at this stage generate multiple sites, corresponding to the same cell from stages 2 or 3



Coarse grid: Two hits



Fine grid: One hit

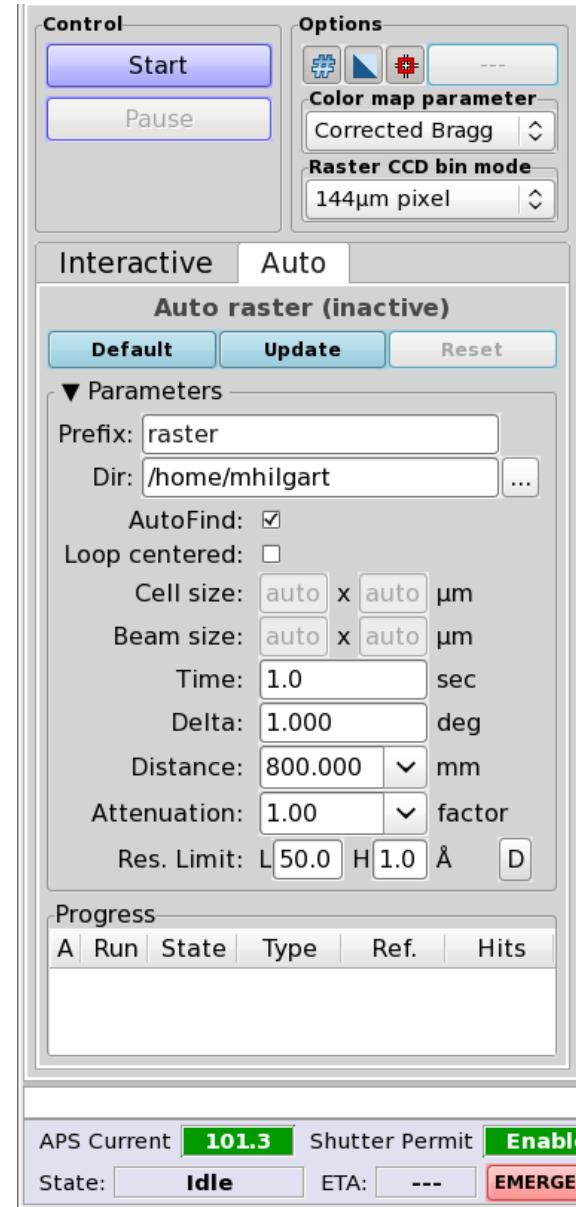


Ortho grid: One hit



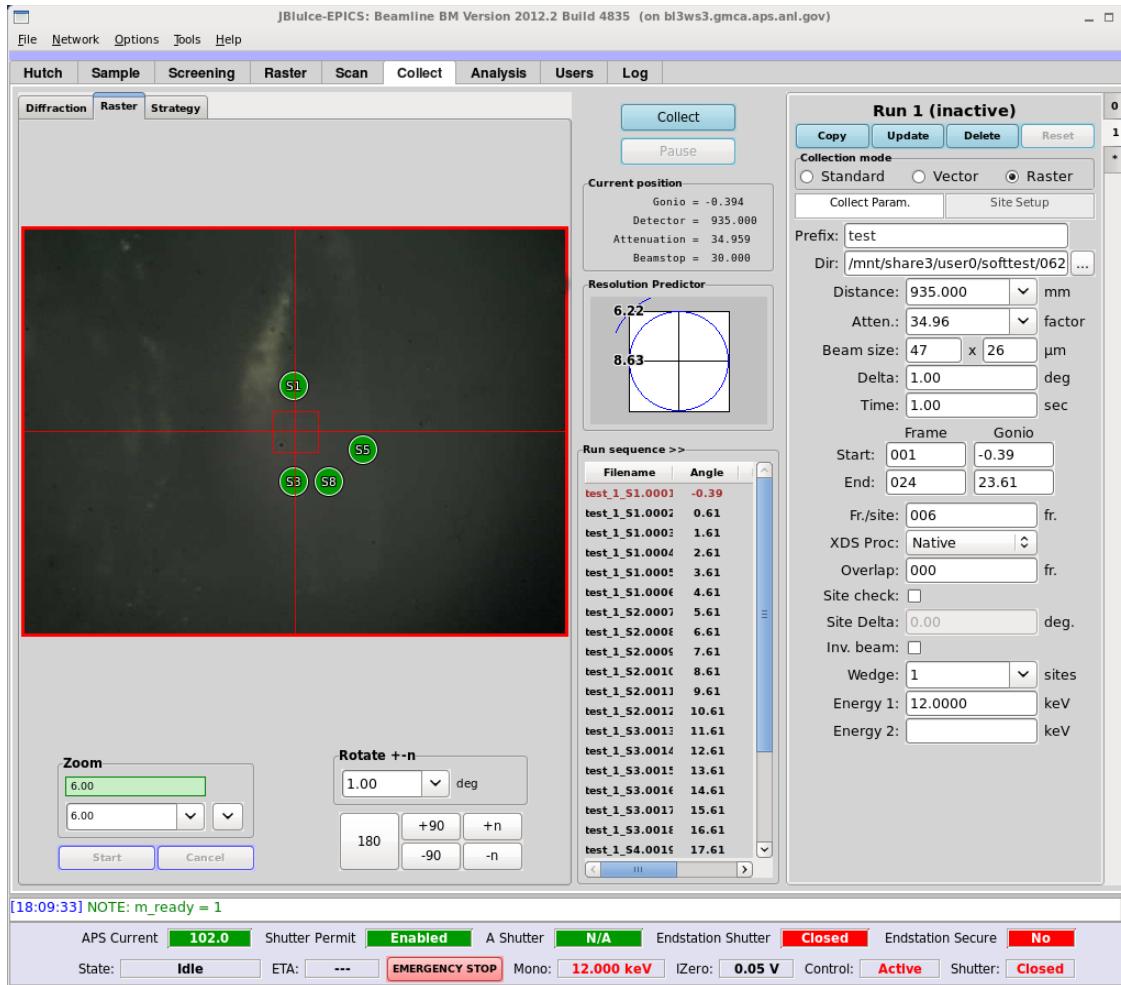
Auto-Raster GUI implementation

- One way to use Auto-Raster is to go directly to the Raster Tab and use the GUI shown at the right
- Auto-Raster is built on interactive raster
 - Interactive raster uses runs like in data collection
 - Runs each have their own collection parameters
 - Users set up each grid manually and then run a search
- Auto mode handles its own set of raster runs but simplifies this for the user
 - A single set of parameters is shown
 - There are some unique parameters to auto mode
 - AutoFind uses optical centering to find the loop and define the initial search outline
 - Resolution limits set the bounds for where to count spots
 - A progress tracker shows the history of grid searches and the results



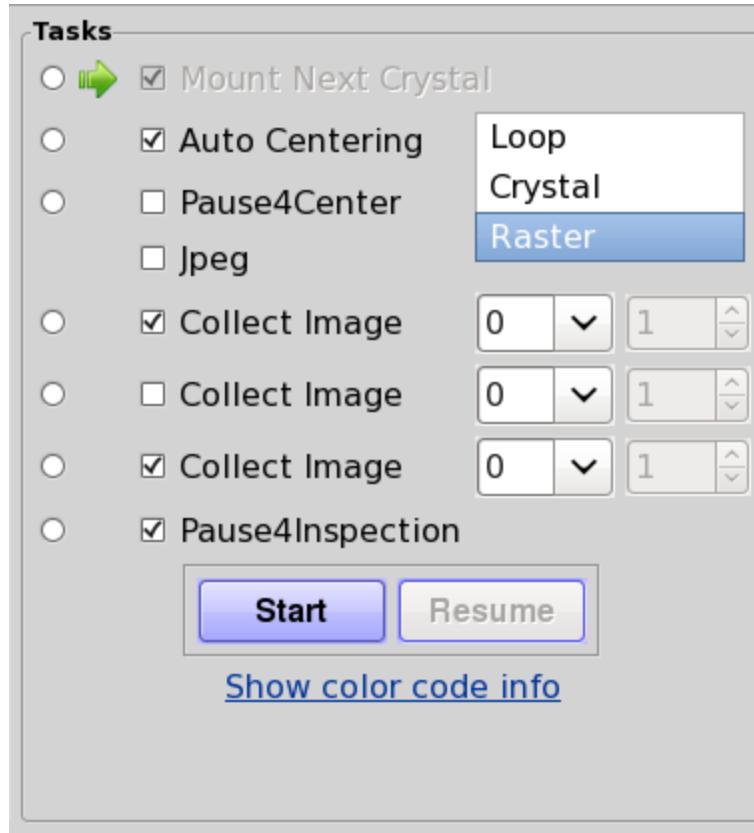
Auto-raster parameters

Auto-Raster GUI implementation



- Auto-Raster sites are sent automatically to the collect tab
 - Sites can be chosen for specific runs in each collect run tab

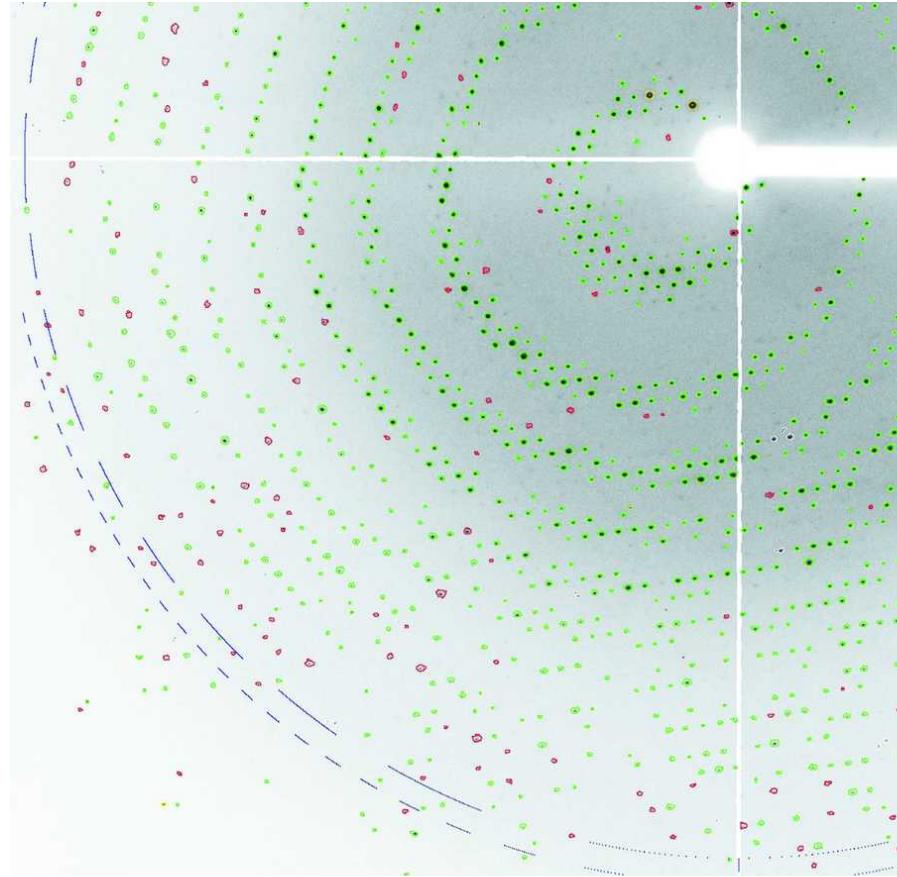
Auto-Raster GUI implementation



- Auto-Raster can be run as a centering method from the screening tab
 - Raster parameters are currently set in the raster tab, we may set defaults in the future
 - In unattended mode, data collection would follow directly after centering

Diffraction Image Analysis

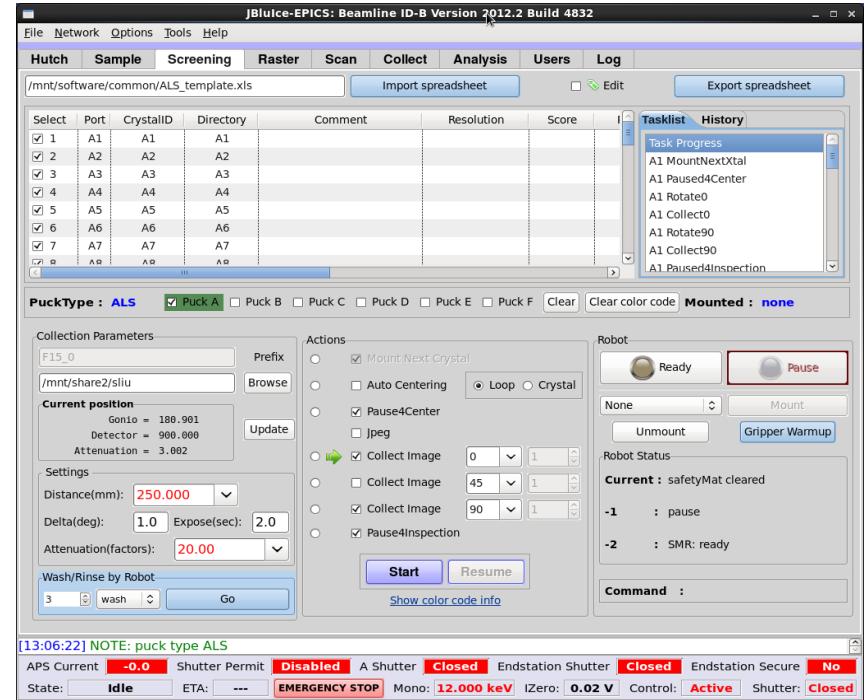
- Analysis is performed on single images, orthogonal image is not taken
- SpotFinder
 - Used at GM/CA, Diamond and SSRL for raster image analysis
 - Analyzes spots and detects ice rings
 - Claims to detect most crystal quality issues
 - Server processes images in parallel (200ms/ image)
- EDNA
 - Used by ESRF for raster image analysis
 - EDNA is a framework which pipelines MOSFLM, LabelIt, RADDSE and BEST
 - Uses auto-indexing to detect when there are multiple lattices, a key advantage
 - Takes longer (5 seconds per image)



Example SpotFinder image:
Green: “good” quality
Red: multiple maxima

Lights-out Operation

- Goal: The user should interact with data acquisition only when necessary
- So we need to support
 - Zero interaction: all choices are made automatically
 - Up-front only interaction: Known parameters are entered before starting
 - Selective interaction: User intervenes only if they see something
 - Checkpoint interaction: Process stops at pre-determined tasks



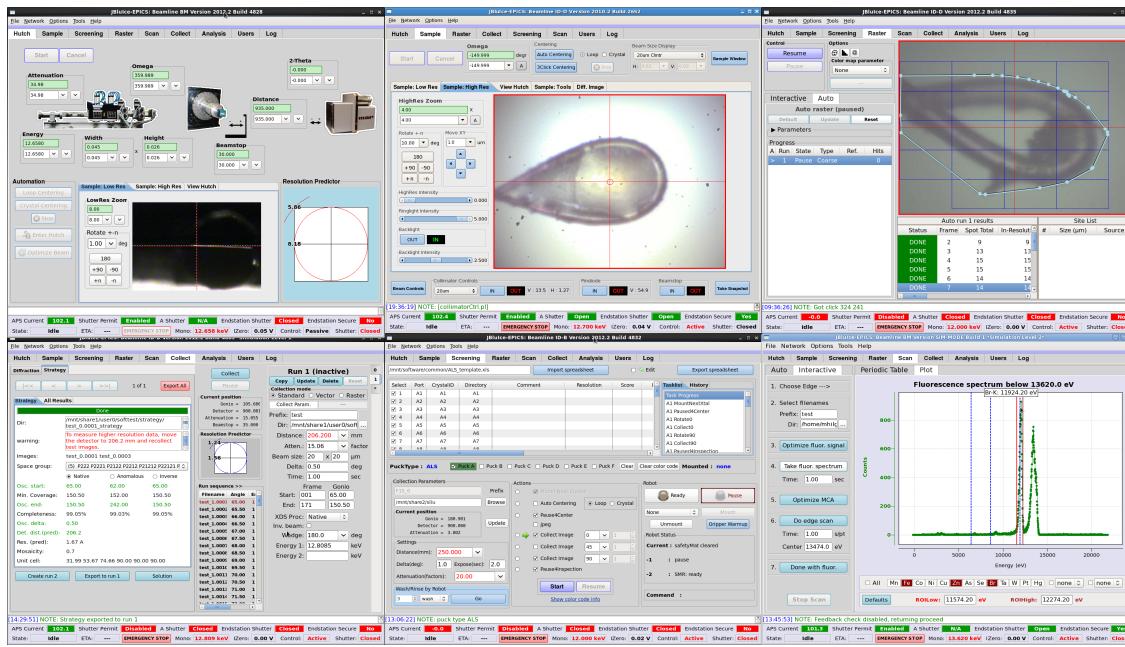
JBlulce Screening Tab: Central to lights-out mode



The data acquisition pipeline: All steps must be automated and linked

Conclusion

- Auto-Raster is a critical link in automation
- It is in the experimental phase now
 - Methods for image analysis are being evaluated for robustness
 - Whether indexing is necessary or not is an important question
- Data collection based on strategy also needs to be linked to screening
- With Auto-Raster and data collection as options on the screening tab, lights-out operation will become a supported mode for general use



JBlulce-EPICS

JBlulce Developers

Mark Hilgart
Sudhir Pothineni

EPICS Developers

Sergey Stepanov
Oleg Makarov

Design Suggestions
and Testing

Craig Ogata
Ruslan Sanishvili
Michael Becker
Nagarajan Venugopalan

Management

Janet Smith
Robert Fischetti