

APS Optics Metrology

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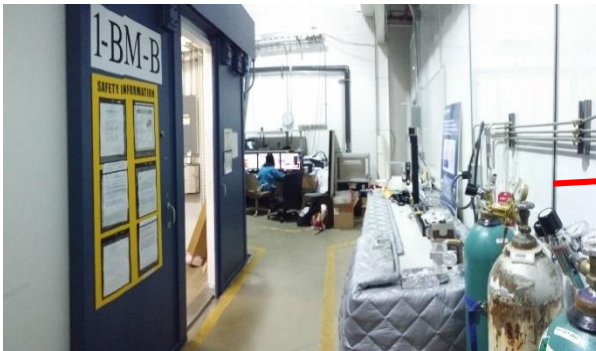
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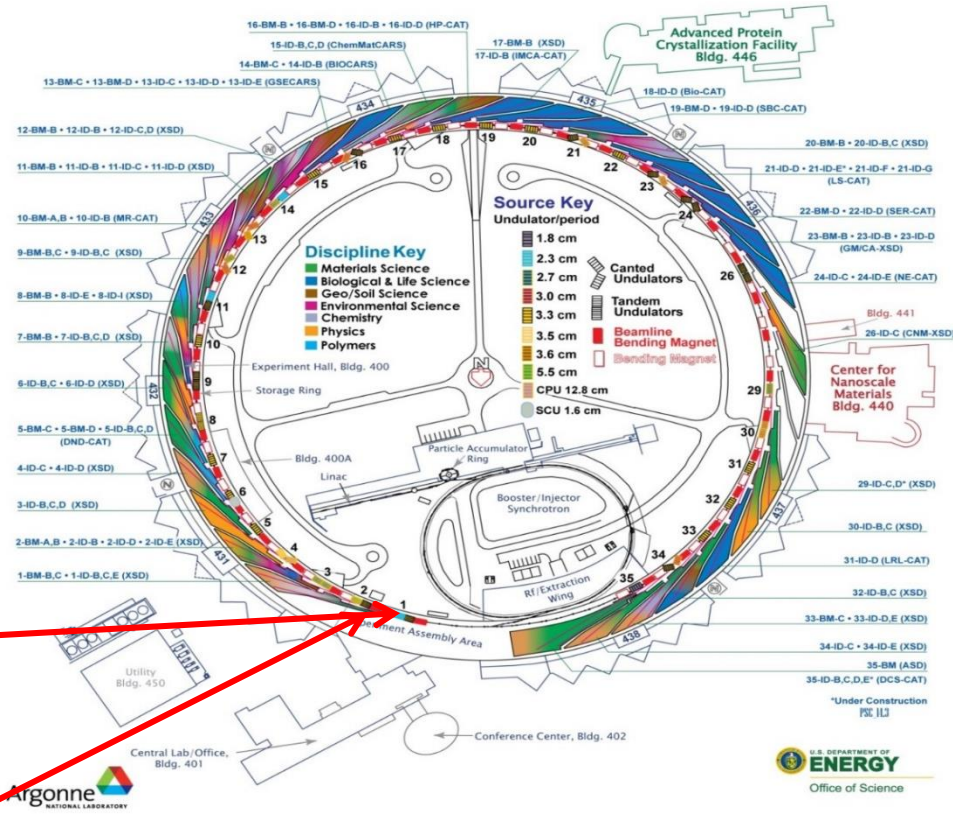


Outline

- Introduction
- Optical Metrology
- At-Wavelength Metrology
- Summary

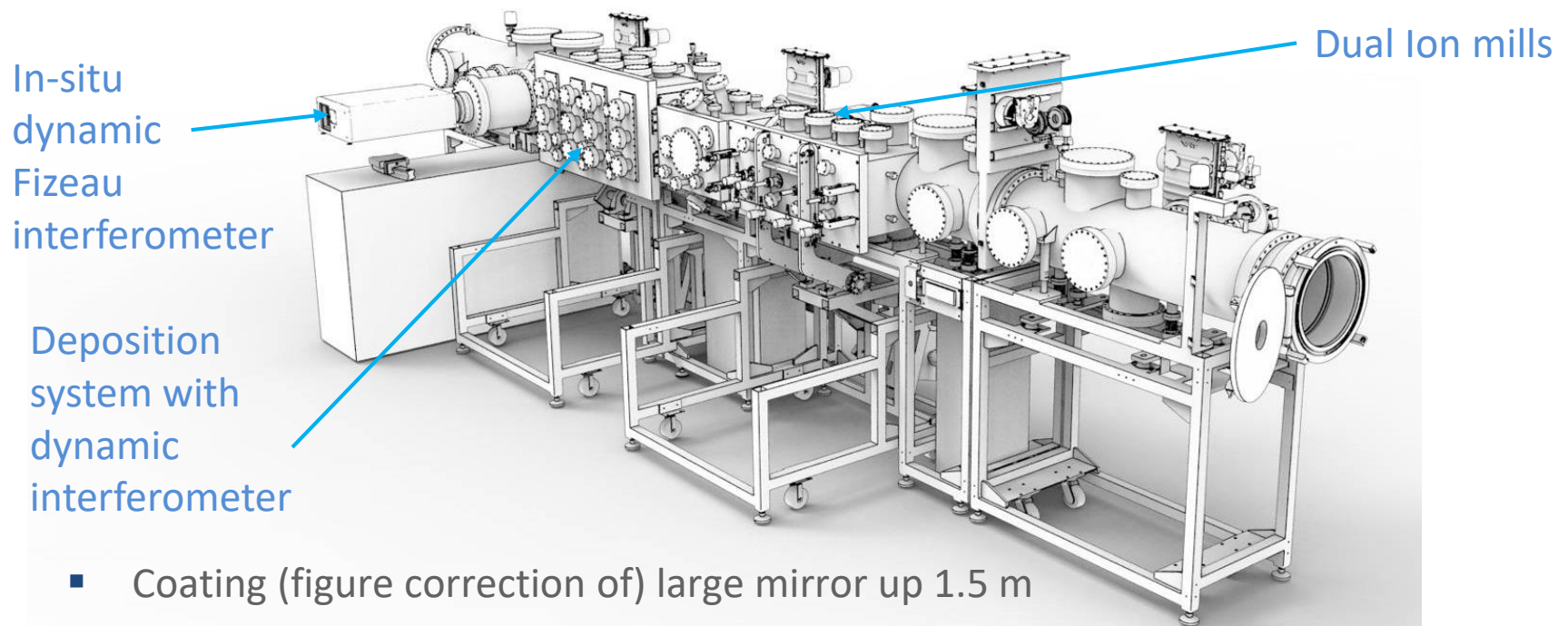


1-BM



New Modular Deposition System with integrated In-situ Ion Beam Milling and Metrology

- Effective use of low-emittance will require optics with dramatically smaller figure errors and tailored surface profiles/
- APS is investing in a new deposition system that allow advanced thin film optics including.

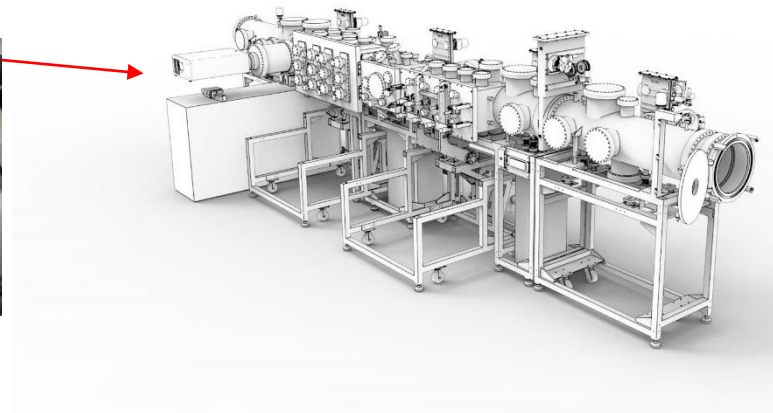
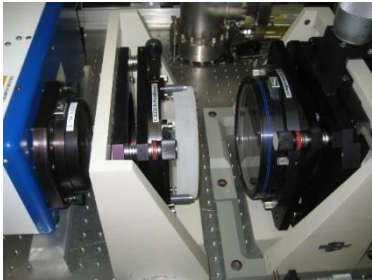


- Coating (figure correction of) large mirror up 1.5 m
- Fabricated coated mirrors and graded multilayer optics
- Delivery expected November. 2015

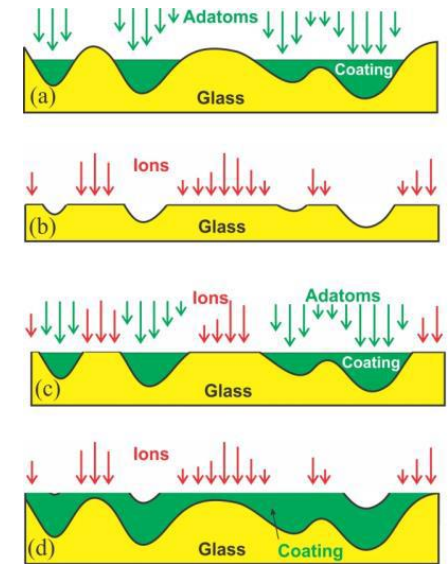
Lahsen Assoufid, APS Metrology updates, TWG Meeting, October 15, 2015

New Modular Deposition System with integrated In-situ Ion Beam Milling and Metrology

- The system includes a Fizeau interferometer for measurement of mirrors profile.
- Maintains the mirror under vacuum through the fabrication process
- Fast iteration rate for recoating/milling
- Ability to avoid oxidation (metals, etc.)



- **Extremely accurate registration between Fizeau and ion mills/coatings for accurate fabrication of optics**
- Coating (figure correction of) large mirror up 1.5 m
- Fabricated coated mirrors and graded multilayer optics

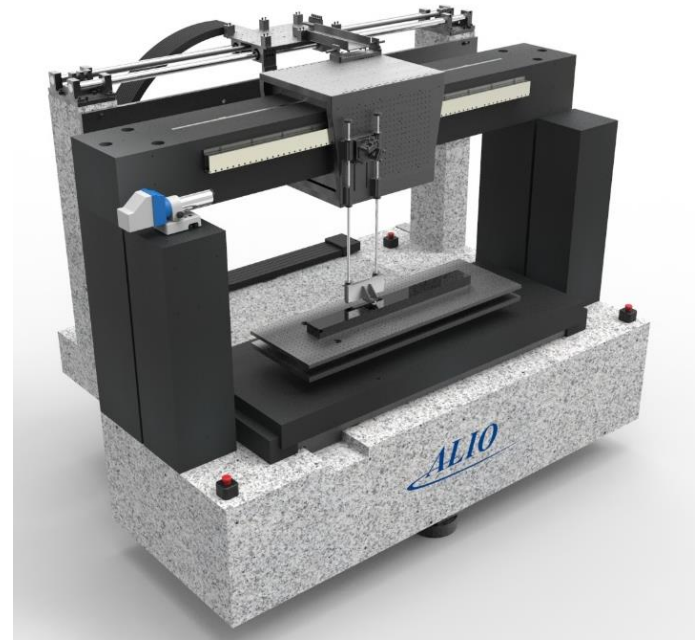


Surface correction techniques: (a) differential deposition, (b) ion-beam figuring, (c) combination, (d) ion-beam figuring of over-coating

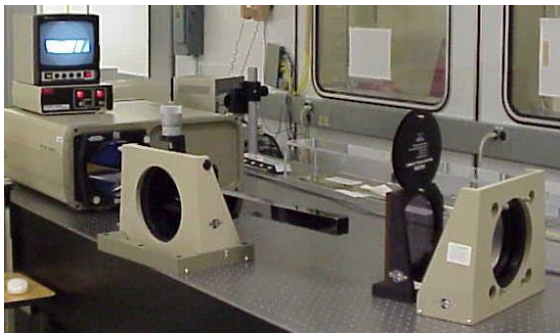
(R. Conley)

Optical Metrology

- Current capabilities:
 - New slope measuring system in the NOM configuration with <50 nrad precision on flat mirrors
 - Roughness and stitching microscope interferometer (MicroXAM RTS), < 0.05 nm height resolution
 - Laser Fizeau Interferometer (Wyko 6000), 150 mm aperture, <1 nm resolution.



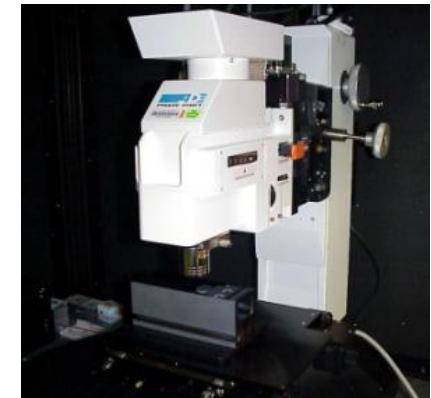
The APS slope measuring profiler (2011-12)



Wyko 6000 Interferometer (1994)

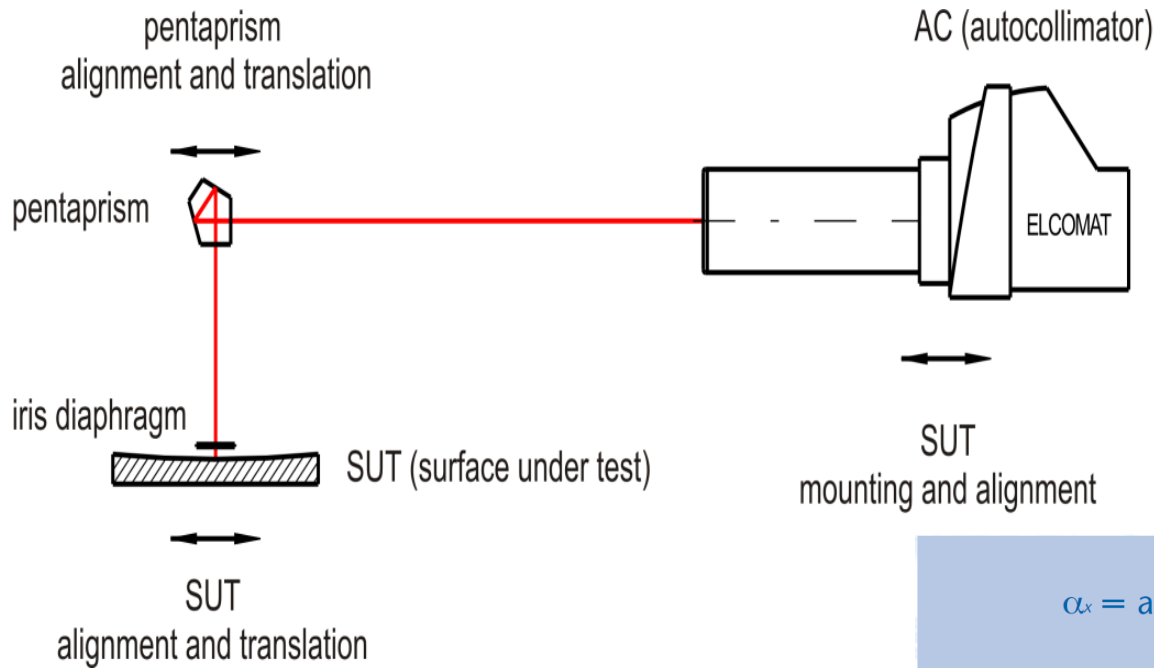


4-D Technology's FizCam for in-situ metrology (2015)



MicroXam RTS roughness/microstitching microscope (2006)

Autocollimator and a moving mirror pentaprism based slope profiler (NOM concept)



Elcomat 3000/8

<http://www.moeller-wedel-optical.com/>

$$\alpha_x = \arctan\left(\frac{\Delta x}{2f}\right) \approx \frac{\Delta x}{2f}$$

$$\alpha_y = \arctan\left(\frac{\Delta y}{2f}\right) \approx \frac{\Delta y}{2f}$$

*F. Siewert, H. Lammert, T. Zeschke, Modern Developments in X-ray and Neutron Optics, Springer 2008



The image of an illuminated object, located in the rear focal plane of the collimator lens, is projected to infinity and reflected via mirror. The image is picked up by a light-sensitive receiver.

A slight alteration of the angle between the optical axis of the autocollimator and the mirror causes a deviation which can be determined very precisely.

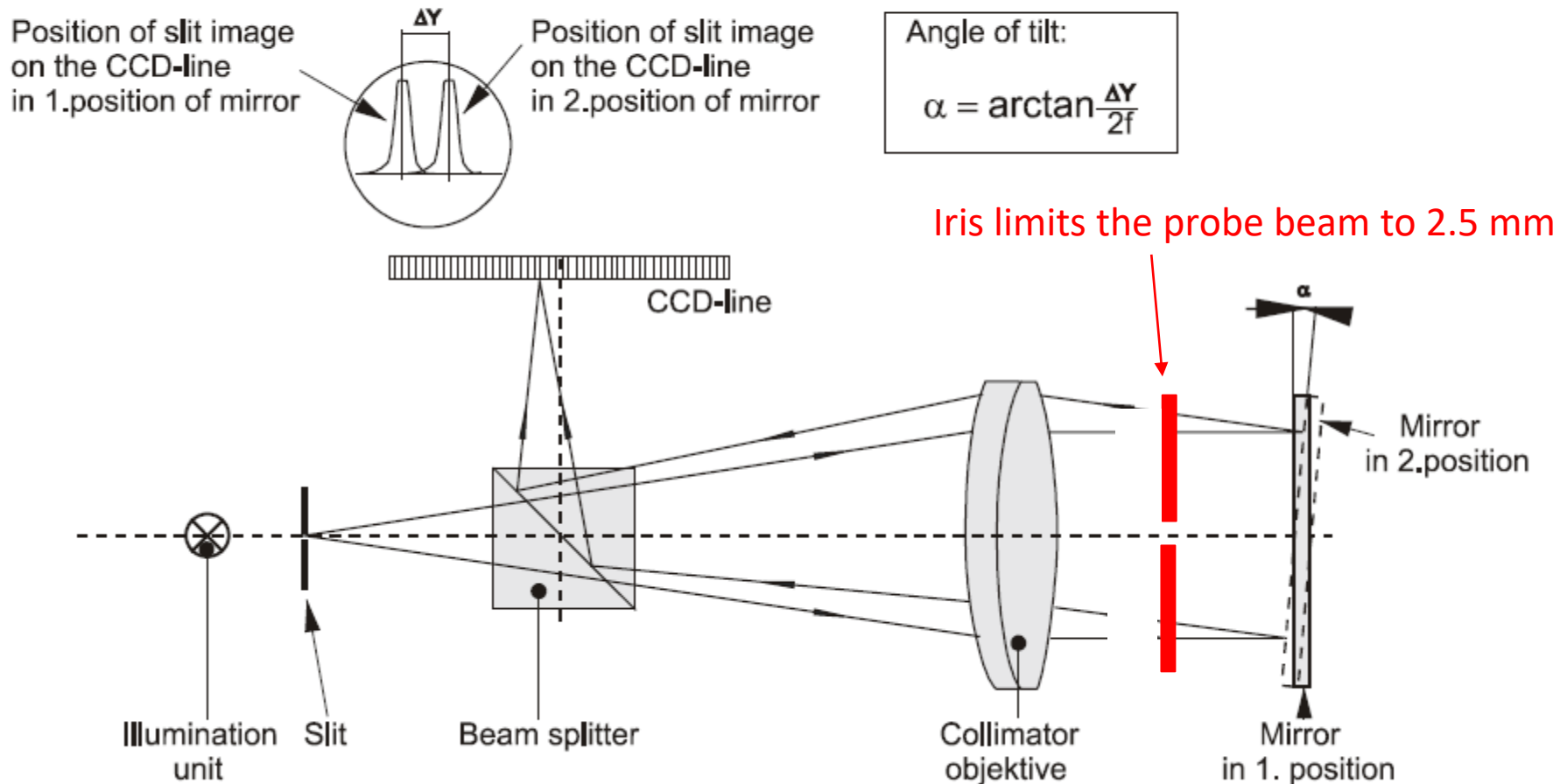


Fig.2: Measuring principle of autocollimation

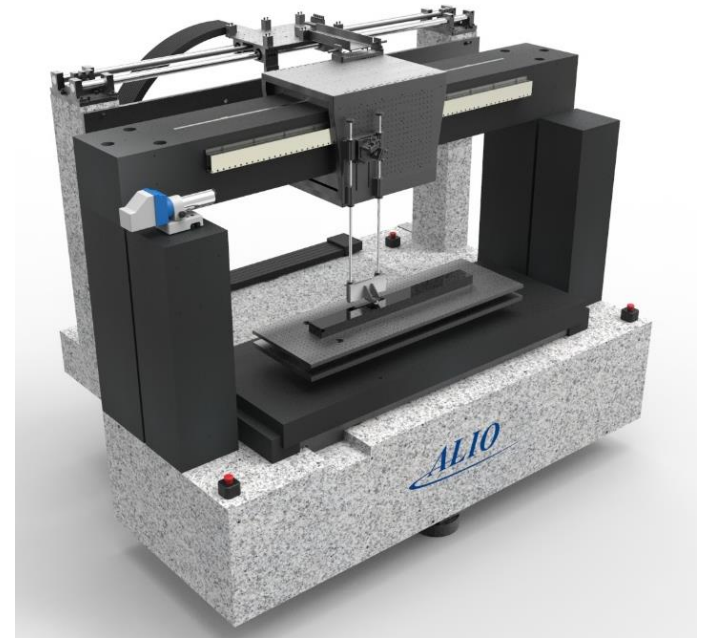
7.1 Autocollimation Measuring Head

Objective lens:	Free aperture	50 mm
	Focal length	300 mm
	Illuminated measuring aperture	ca. 32 mm
Light sources:	High power LED	
	Wave length 660 nm	
Detectors:	CCD elements	
Adjustment and alignment aid:	Laser attachment D65 (to be ordered separately)	
FOV:	approx. 57 arcmin	
Measuring range:		
- total range	± 17.5 arcmin (corresponds to $\pm 1050''$)	
- distance autocollimator/mirror:	up to 2500 mm:	$\pm 1000''$
	up to 3000 mm (theoretical):	$\pm 885''$
	up to 7000 mm (theoretical):	$\pm 365''$
Measuring rate:		25 Hz
Measuring accuracy:		
- for any 20'' measuring range (in absolute measuring mode)		$\pm 0.10''$
- for the entire measuring range		$\pm 0.25''$
(The measuring range depends on the measuring distance, see above.)		
Display-resolution:		0.005''



The APS slope measuring profiler design

- Gantry System:
 - Alio Industries (APS Design)
 - Scan length up 1.5 m
- Slope sensor
 - Autocollimator: Elcomat 3000/8, MÖLLER-WEDEL OPTICAL GmbH, model
 - Resolution ~ 50 nrad
- scanning opto-mechanics and mirror support table: APS
- Data acquisition: EPICS based, APS BCDA
- Data processing: Python-based, APS



LTP 3-D drawing by O. Schmidt

The APS Slope Measuring Profiler: The Gantry System Design

Additional Mounting Location for Additional User Added Functionality.

Soft / Gentle Cable Loop from Cable Axis to Metrology Axis for Motor and Encoder Cables.

Cable axis

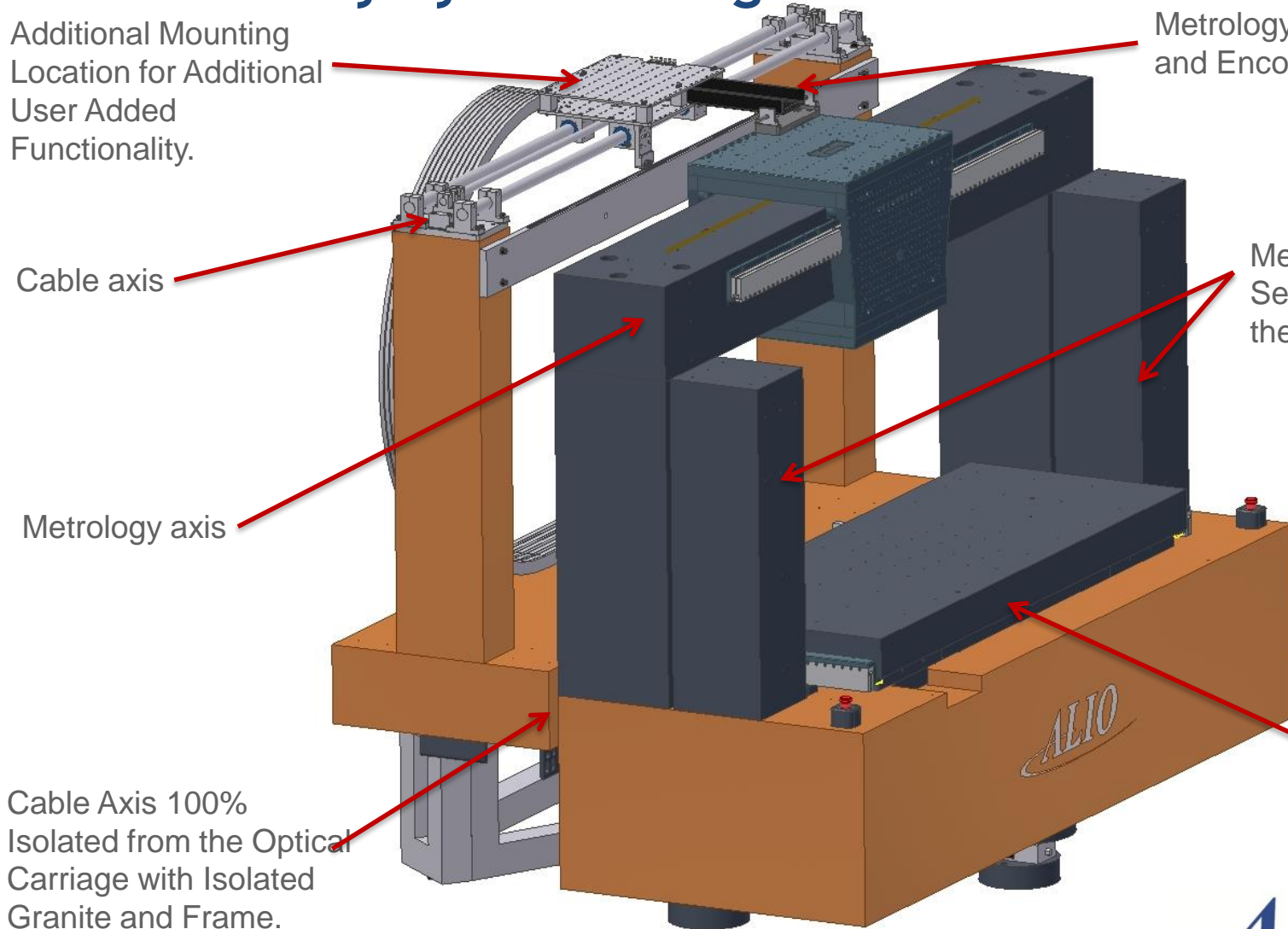
Metrology Risers Separate / Isolated from the Axis / Motion Risers

Metrology axis

Positioning accuracy 50 nm. A factor of 2000 improvement over previous LTP

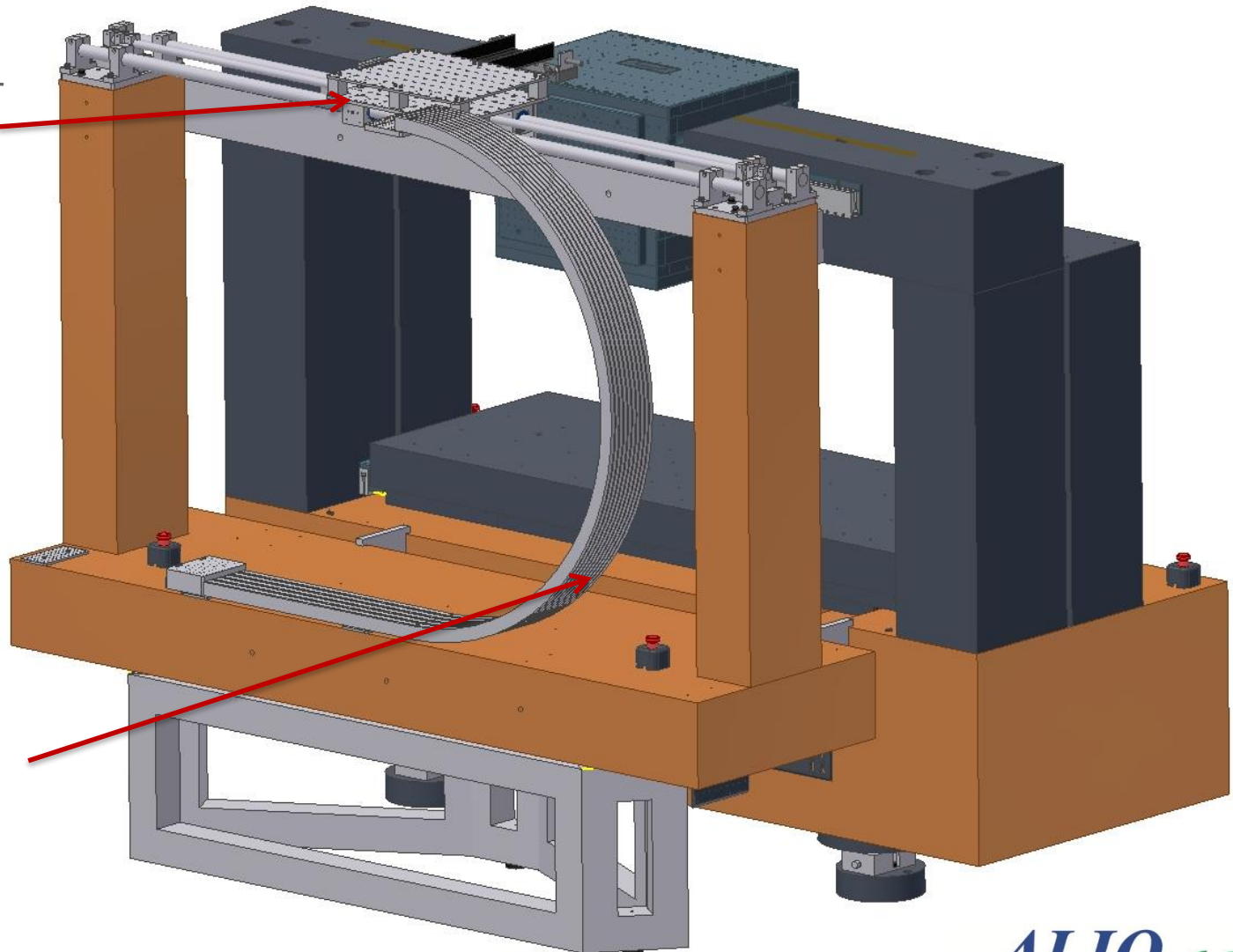
Cable Axis 100% Isolated from the Optical Carriage with Isolated Granite and Frame.

Mirror granite table



The APS Slope Measuring Profiler: The Gantry System Design

Completely Separate Air Bearing Servo Axis for Cable Axis. Axis Mirrors Motion of Optical Carriage Thus Isolating Cable Drag and Vibration.



Large Radius Cable Loop to Minimize Vibration and Drag.

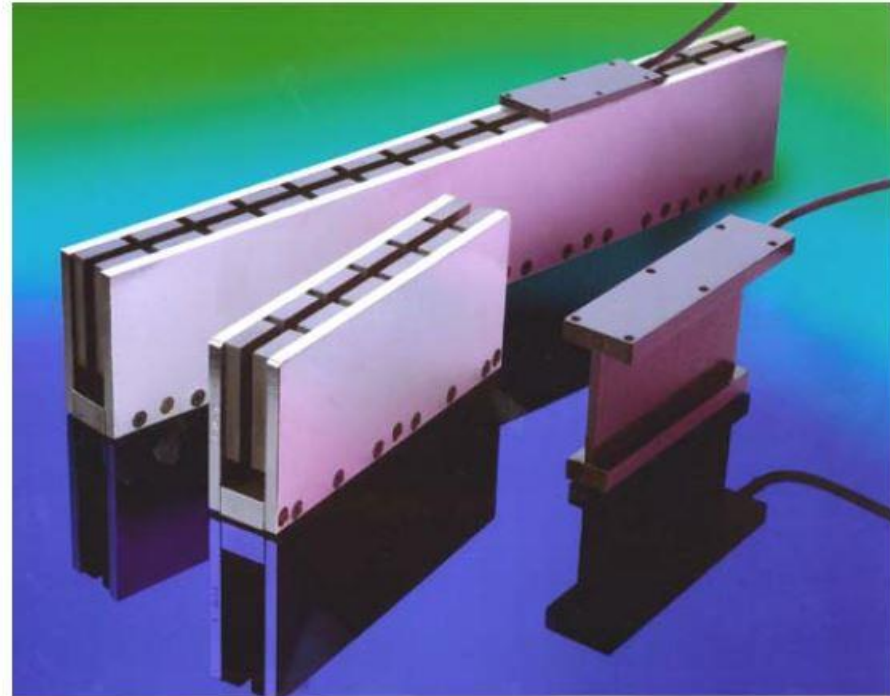
Motion system

P20 Motor Data

Brushless Linear Servo Motors designed for Advanced Motion Applications

Designed for today's most advanced applications, Airex Brushless Linear Servo Motors offer the absolute best in linear motion technology.

Airex patented machine winding technology produces motors with exceptional performance, smooth motion, high accuracy, unmatched



FEATURES:

http://www.airex.com/wp-content/Linear_Motr/P20%20Motor%20Data%20f.pdf

Motion system specs and test results

Table 1. Test results with specifications for the Long Trace Profiler system: X axis

TEST	TEST METHOD	TEST LOCATION	SPEC	ACTUAL
<u>X AXIS</u>				
TRANSLATION RANGE	CONTROLLER (1)	ANL	1500 mm	1520 mm
MINIMUM VELOCITY	CONTROLLER (1)	ANL	0.1 mm/sec	verified
MAXIMUM VELOCITY	CONTROLLER (1)	ANL	20 mm/sec	verified
ACCURACY (GLOBAL)	LASER (2)	ANL	+/- 3 um	+/- 0.277 um
ACCURACY (LOCAL)	LASER (3)	ANL	+/- 0.3 um / 100 mm	+/-0.172 um
REPEATABILITY (GLOBAL MOVE)	CAP GAUGE (4)	ANL	+/- 500 nm @ 1 σ	+/- 24 nm (1 σ)
PITCH (TILT) REPEATABILITY (THETA Y OF X CARRIAGE)	CAP GAUGE (4,5)	ANL	+/- 100 nrad @ 1 σ +/-xx nm @ x00mm (1 σ)	+/- 33 nrad (1 σ)*
YAW (TILT) REPEATABILITY (THETA Z OF X CARRIAGE)	CAP GAUGE (4,5)	ANL	+/- 100 nrad @ 1 σ +/-xx nm @ x00mm (1 σ)	+/- 54 nrad (1 σ)*
ROLL (TILT) REPEATABILITY (THETA X OF X CARRIAGE)	CAP GAUGE (4,5)	ANL	+/- 100 nrad @ 1 σ +/-xx nm @ x00mm (1 σ)	+/- 79 nrad (1 σ)*
PITCH	LASER (2)	ANL	+/- 5 urad (+/- 1 arc-sec)	+/- 2.6 arc-sec
YAW	LASER (2)	ANL	+/- 5 urad (+/- 1 arc-sec)	+/- 0.5 arc-sec
ROLL (DUAL FLATNESS)	LASER (2)	ANL	+/- 5 urad (+/- 1 arc-sec)	+/- 1.25 arc-sec
FLATNESS	LASER (6)	ANL	N/A	+/- 3.7 um
STRAIGHTNESS	LASER (6)	ANL	N/A	+/- 1.7 um
CURRENT DRAW ON AMPLIFIER	CONTROLLER (1)	ANL	< 1 W	<< 1 W

Delivery of the gantry system: August 2011



Assembling and Installation: Sept - Oct. 2011



Mahsen Assoufid, APS Metrology Updates, TWG Meeting, October 15, 2015

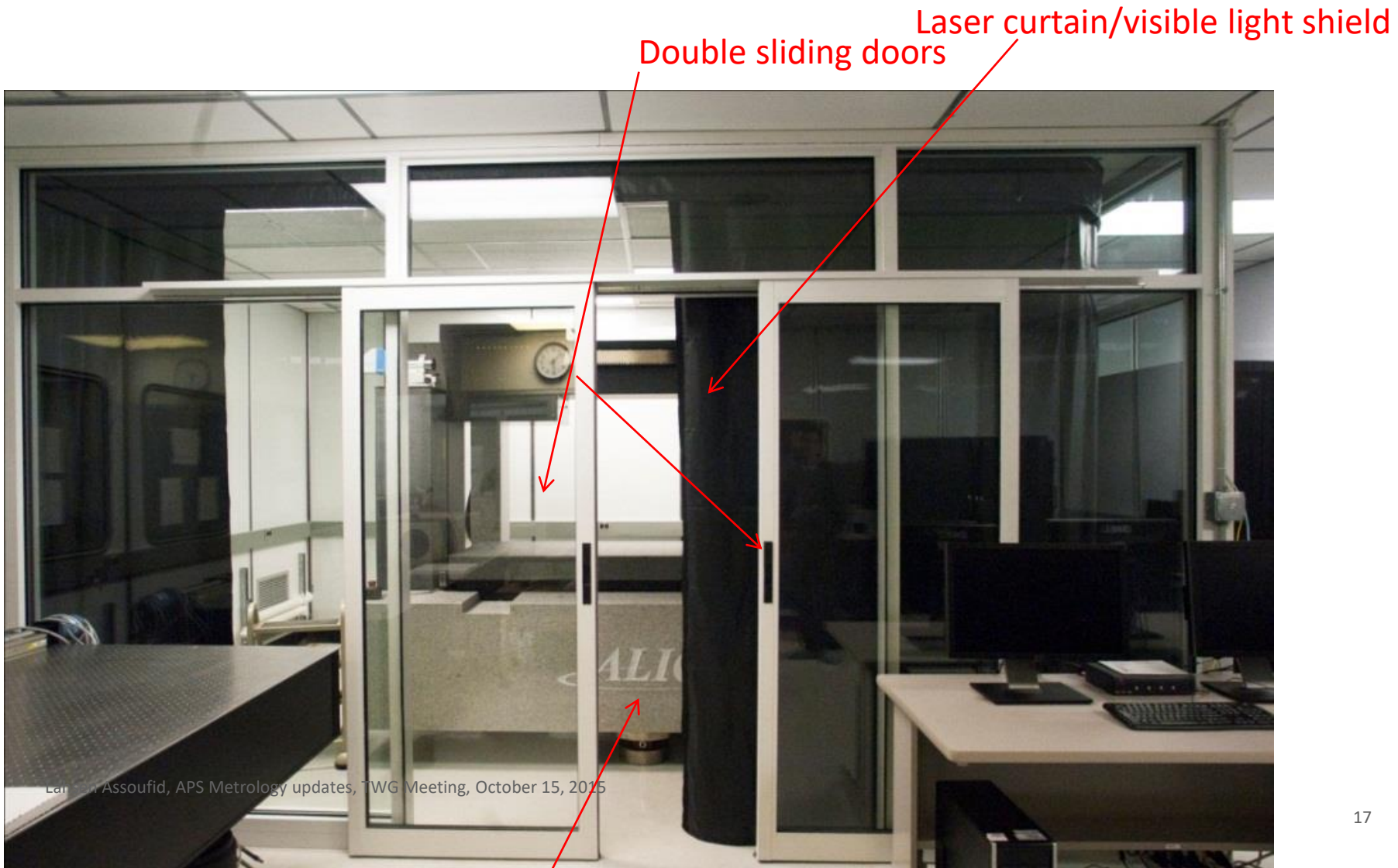
Construction of the Enclosure Nov. 2011



Lahsen Assoufid, APS Metrology updates, TWG Meeting, October 15, 2015



Enclosure construction: Dec. 2011



Granite table supported on an industrial kinematic mount
Has a separate air handling control



Commissioning Jan. 2012

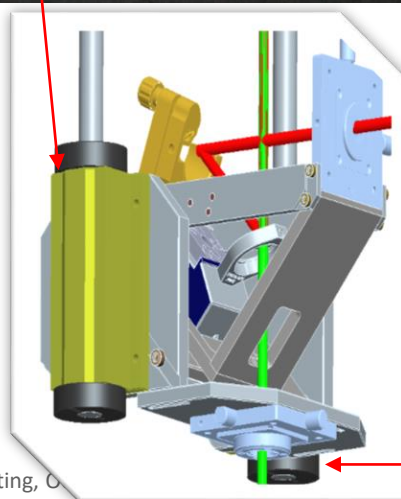
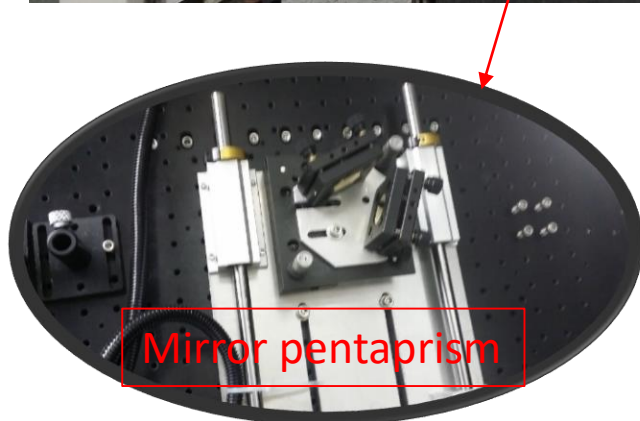
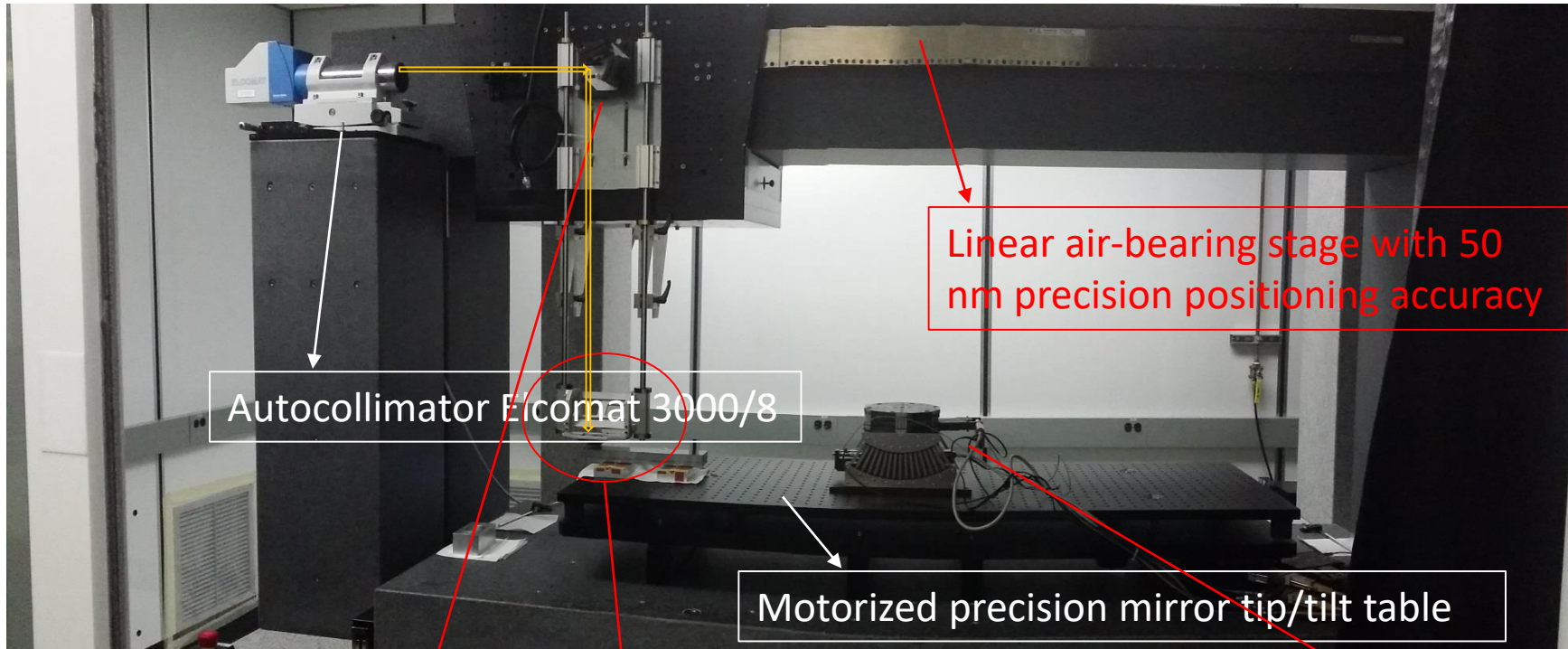
Light switch

Control electronic



Switch for air flow system (baffle)

APS Slope Measuring Profiler in NOM Configuration



Mirror pentaprism for measurement of horizontal deflecting mirror

Small angle generator for angle calibration and for curved mirror measurement by stitching

2.5 mm diam iris

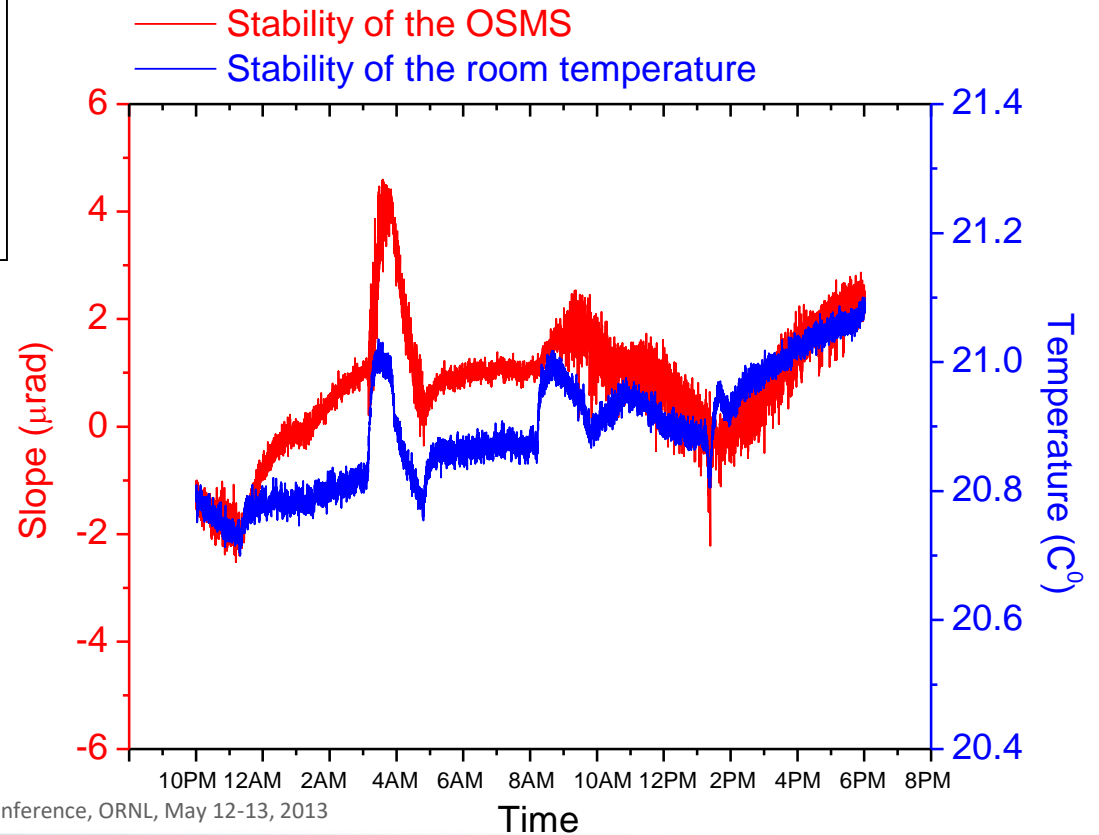
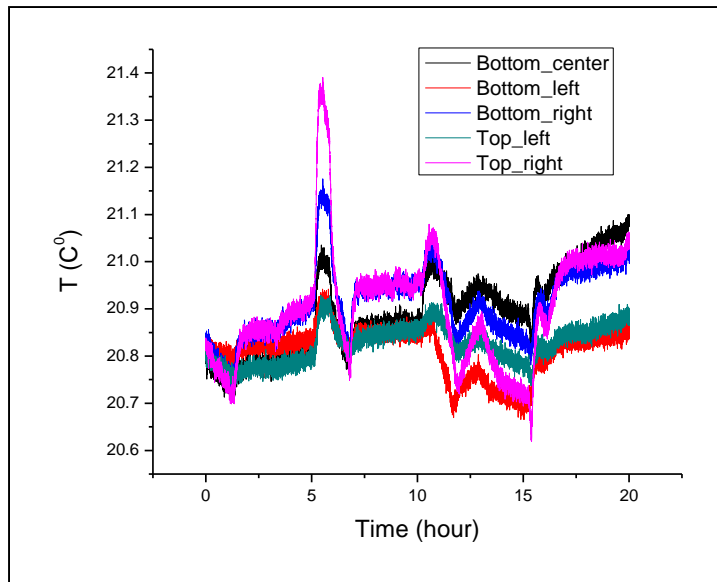
EPICS-based Data Acquisition (2011-12)

The screenshot displays the EPICS-based data acquisition software interface. The main window is titled "Measurement_Scan.adl" and "Measurement Scan". It features several control panels and data displays:

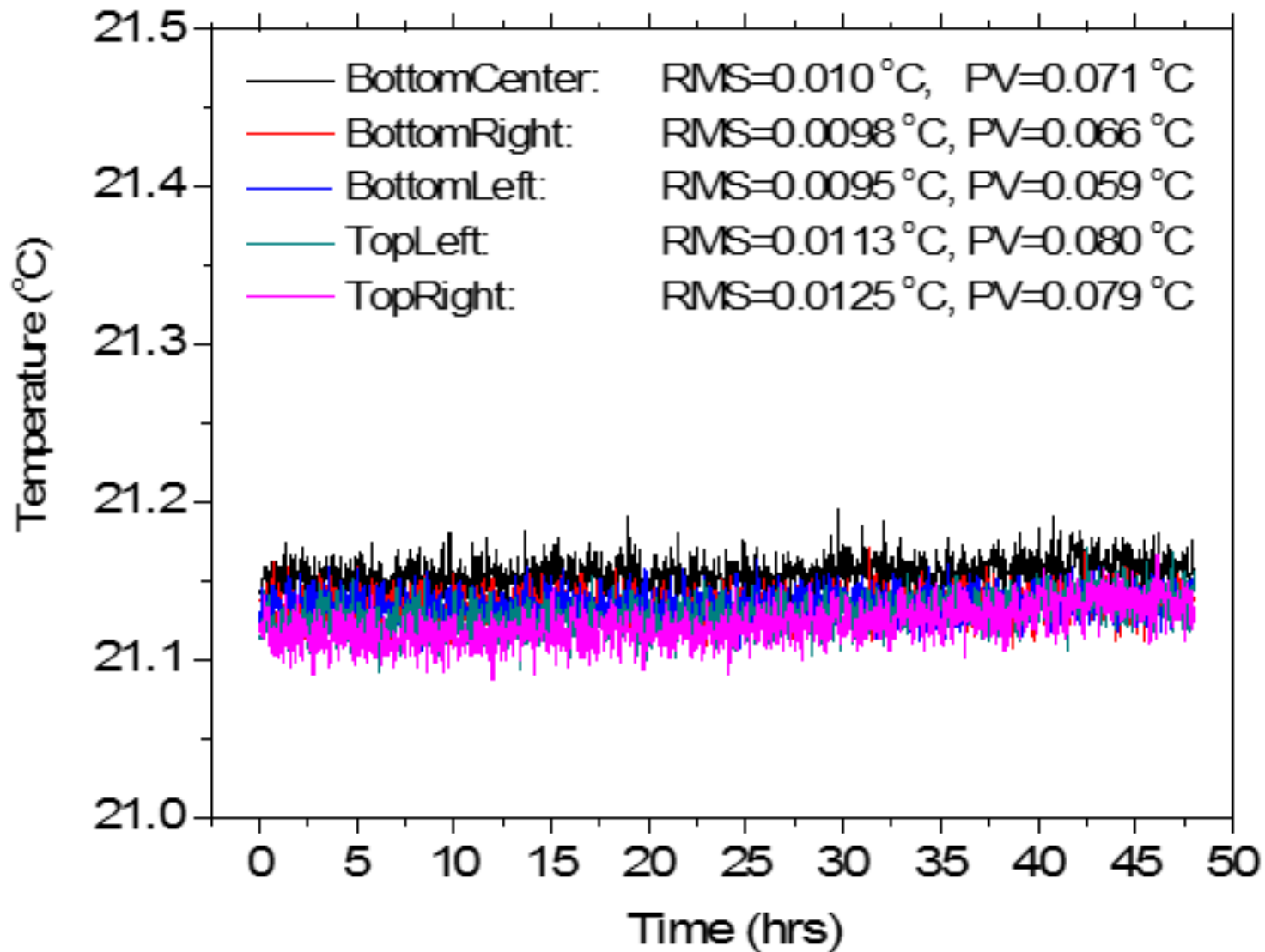
- Motor Control:** Includes "motor?x.adl" and "motor?y.adl" panels for controlling Alio X and Alio Y motors, and "motor?z.adl" for Tilt, Tip InBoard, and Tip OnBoard. A "Motor" label points to these panels.
- Scan Control:** A central panel with "Load", "Scan", "GO PAUSE", and "ABORT" buttons. It shows scan parameters like "Scan 1 of 1", "Measurement Position 56 of 56", and "X Position 549.9999". A "Scan Setup" section includes fields for Start, End, Increment, Settling Time, and Number of Samples to Average. A "Scan Status" label points to this area.
- Data File Setup:** A panel on the right titled "Data File" for saving data. It includes fields for "Base Name" (La_Test), "Next scan number" (5), and "Save status Active". It lists data points to be saved, such as "Mirror Measurements", "Motor Positions", "Room Temperature", and "Elapsed Time". A "Data Plot" label points to this section.
- Data Plots:** Two "scanDetPlot.adl" windows at the bottom show real-time data plots. The left plot shows "Y=1tp:ElcomatAM1:Xavg.VAL" vs "1tp:SM1.VAL". The right plot shows "Y=1tp:ElcomatAM1:Yavg.VAL" vs "1tp:SM1.VAL". A "Slope Data" label points to these plots.
- Annotations:** Yellow arrows and labels point to various parts of the interface: "Scan Start Status" points to the top buttons; "Scan Setup" points to the central control panel; "Motor" points to the motor control panels; "Data Plot" points to the data file setup panel; and "Slope Data" points to the data plots.

J. Sullivan, P. Jemian, L. Assoufid EPICS Based Data Acquisition (unpublished)

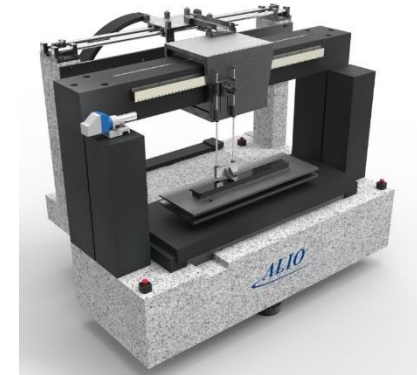
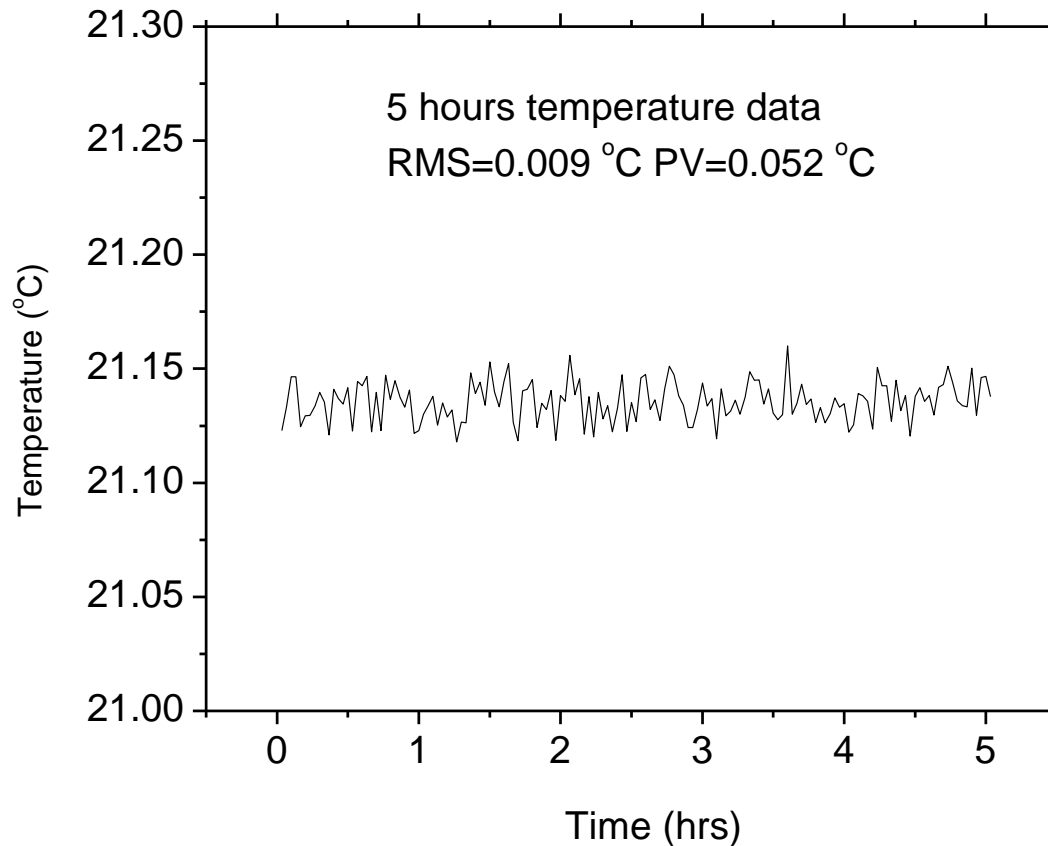
Stability of the APS OSMS vs. the stability of the room temperature in 20 hours



Temperature inside of the AC-LTP enclosure (48 hours from 5/23/2014 to 5/25/2014)



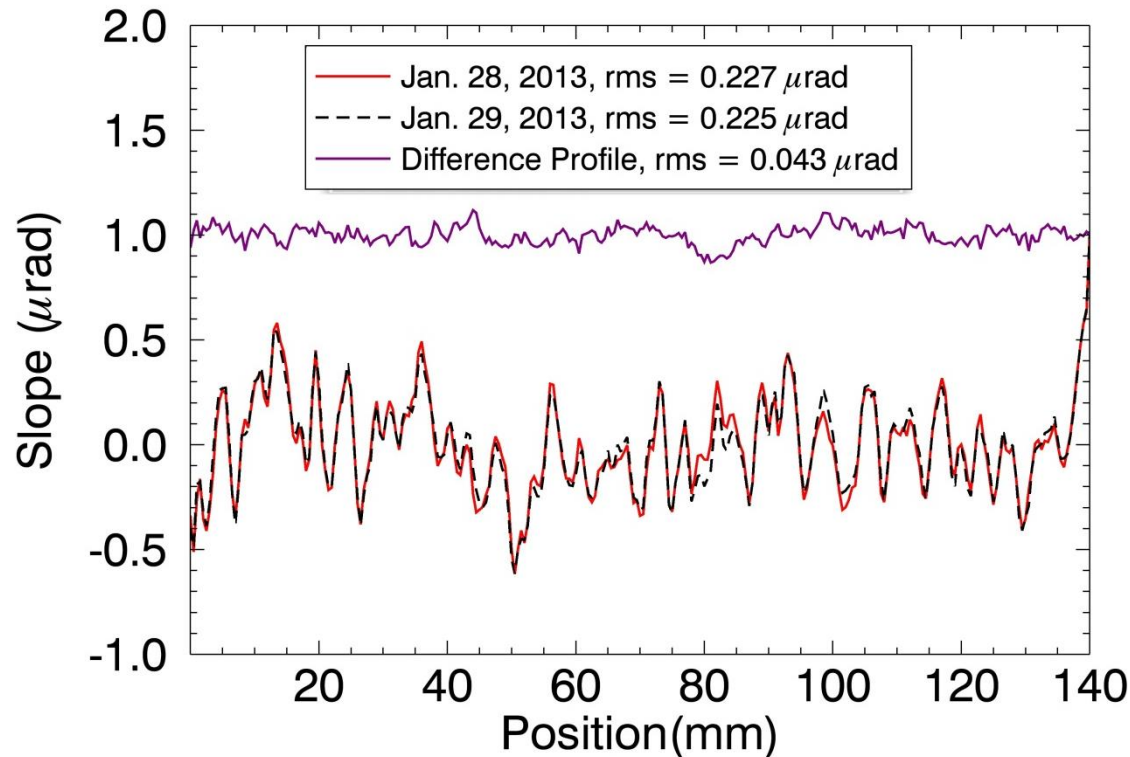
Temperature stability: 2015



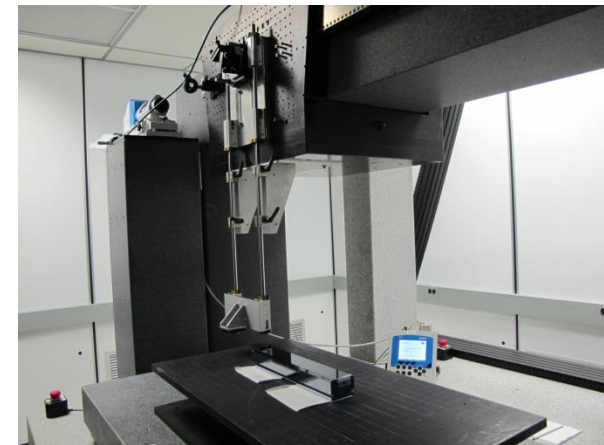
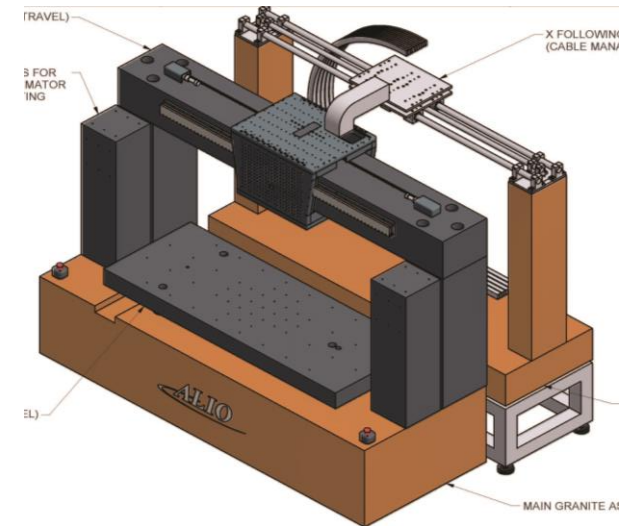
- Air handling system turned off
- Excellent temperature stability obtained within a few hours.
- Further improvement are expected to be achieved by adding another enclosure around the instrument.

New Slope Profiler: Repeatability and accuracy

- Test mirror: 140-mm Si, 0.2 μrad rms slope error
- Two different measurements taken at 1 day interval

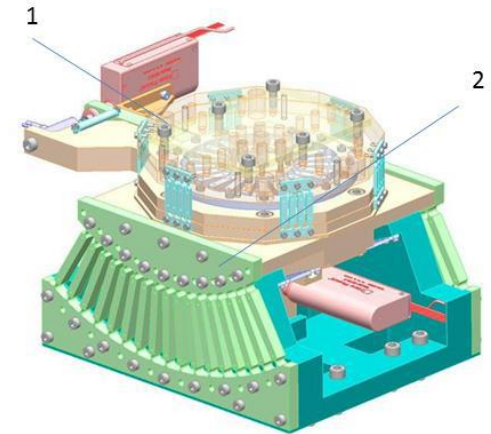


- **Repeatability: 43 nrad rms. A factor of 5 increase in accuracy compared to a standard LTP**



Recent In-house Developments and Implementations

- **New Python-based data processing software: (OMEN)**
- **Calibration**
 - Prototype of a small angle generation device for calibration was developed and tested:
 - Flexural stage (by D. Shu)
 - EPICS-based control and acquisition software (J. Sullivan)



- **Measurement of curved optics by stitching or calibration**

- Automated tip/tilt stage and sub-aperture/segmented measurements
- EPICS-based control and data acquisition software.
- All developed in-house.

- Fine adjustment driven by a PZT with a maximum range ~ 0.6 mrad with 20 nrad resolution.
- Limitation: Coarse adjustment driven by a PicoMotor with a range of up to 9 mrad

Deming Shu, et al. SPIE
Vol. 9206 (2014)

Automated tilting stage for subaperture scanning and stitching: EPICS user interface.

Completed August 2015

- In-house developed software for high precision mirror tilt and positioning for sub-aperture scanning and stitching.

Measurement Scan

Load Scan Segments GO PAUSE ABORT

SCAN Complete

Passes 0 of 7 X Position (urad) 0.00003
 Scan 5 of 5 Y Position (urad) -0.00009
 Measurement Position 95 of 95

X Slope (microrad) -2701.7 Y Slope (microrad) 3637.5
 Temperature (C) 0.0000

Measurement Setup

X Axis Tilt Mirror
 Start 0.00000 mm Table Length 40.000 mm
 End 47.00000 mm Segments 4 7
 Increment 0.50000 mm Segment Size 10.000 mm

Settling Time 0.7500 sec
 Number of Samples to Average 50
 Number of Scans 5
 Temperature Sample Interval 60.000 sec

Backward Mode Sequence Select 1
 Rotation Forward Only
 Return Forward/Backward
 FWD-BCK-BCK-FWD
 F-B-B-F-B-F-F-B

X/Y Slope Alignment

Flexural Stage Tilt Tip OB Tip IB
 Stepper Motor Stage 0.01552 -0.04892 -0.43063
 Load

Forward 0.00000 0.00000 0.00000 urad
 Backward 0.00000 0.00000 0.00000 urad

Save Data

Subdirectory FY2015_LTP/15076 Bing 9-1-2015
 Base Name M15076_
 Next scan number 2
 Save status Active
 Wrote data to M15076_0001.mda

Mirror Measurements

ltp:scan1 ltp:ElcomatAM1:Xavg.VAL Plot
 ltp:ElcomatAM1:Yavg.VAL Plot

Motor Positions

ltp:scan1 ltp:SM1.VAL Plot
 ltp:SM2.VAL Plot
 ltp:m1.VAL Plot

Room Temperature

ltp2:scan1 ltp2:D1Ch2_raw.VAL Plot
 ltp2:D1Ch3_raw.VAL Plot
 ltp2:D1Ch4_raw.VAL Plot
 ltp2:D1Ch5_raw.VAL Plot
 ltp2:D1Ch6_raw.VAL Plot

Elapsed Time

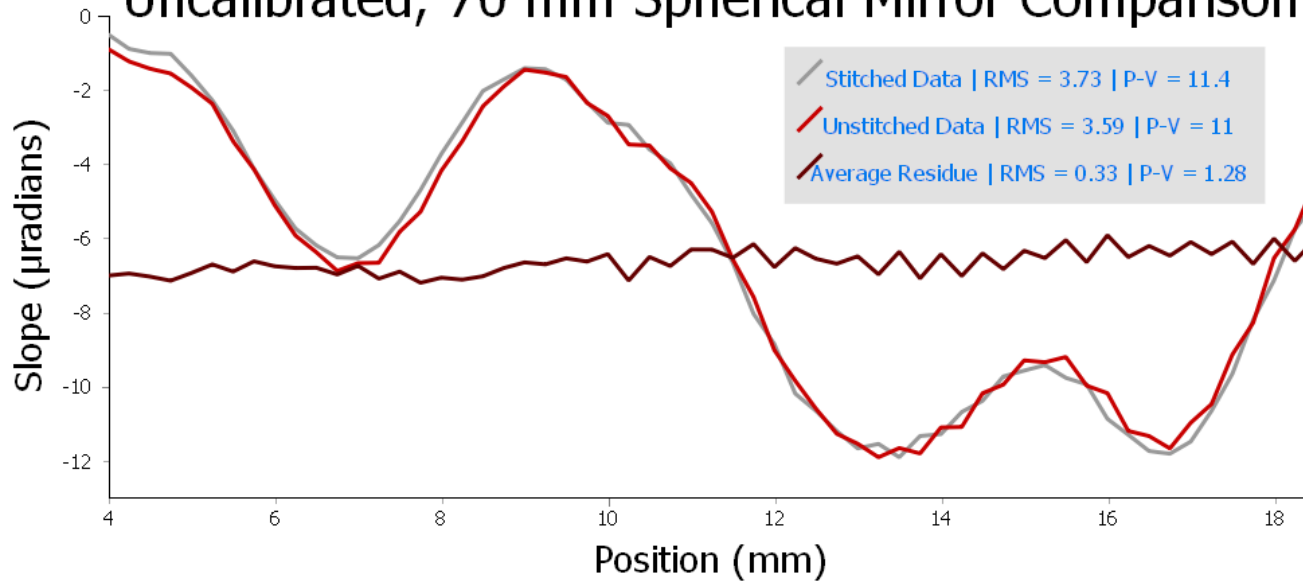
ltp:scan1 ltp:timer1:elapsedSecs Plot

Instruments

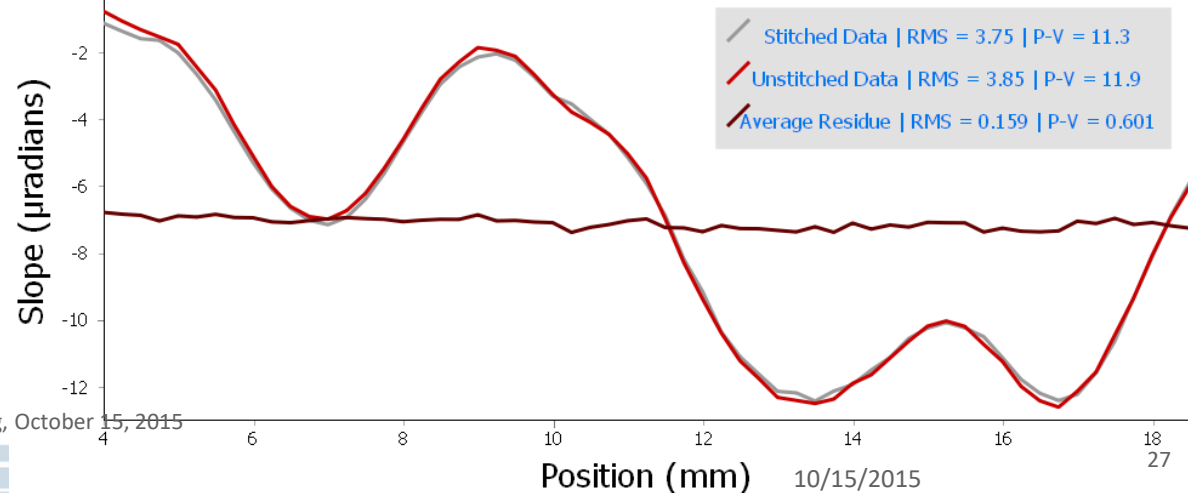
Debug1
 Debug2

Measurement of a Curved Mirror by Stitching: Comparison with Calibrated data

Uncalibrated, 70 mm Spherical Mirror Comparison



Calibrated, 70 mm Spherical Mirror Comparison



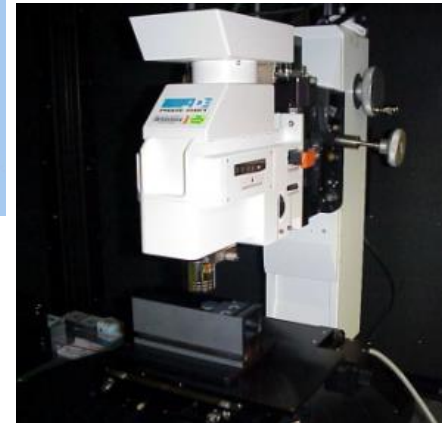
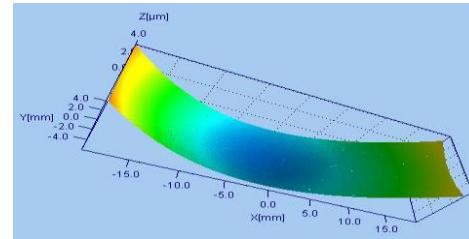
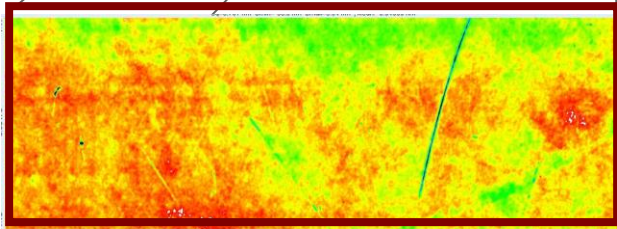
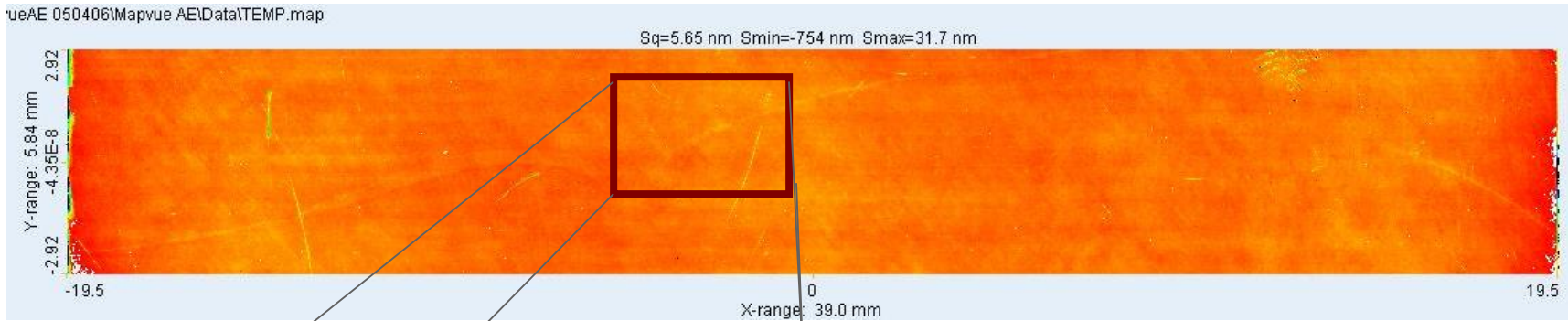
General issues about scanning deflectometric profilers

- Deflectometers (pencil beam LTP, NOM), are typically one dimensional profilers. Characterization of focusing optics generally requires two dimensional metrology tools. (Bender twist can not be easily “seen” with 1-D profilers)
- Scanning devices require long measurement time, which makes the measurement prone to drift error.
- Their variable optical path length make them prone to external perturbations
- Measurements can be affected by:
 - systematic/residual errors of scanning stage (in addition to aberrations of the internal optics)
 - Possible non linearity of the slope sensor
 - Environment effect: temperature stability, electronic and acoustic noise
- Very large (> a few km) and very small (<100m) radii of curvature are very challenging to measure

Autocollimator-based profilers limitations and needs

- Auto-collimator-based slope measuring profilers limitations:
 - Spatial sampling limited by the size of the probe beam (~ 2.5 mm).
 - Measurement of curved mirrors limited by the autocollimator dynamical range and (few 10 microrads) and non linearity for steep sloped surfaces.
 - Require precise calibration or and sub-aperture/segmented measurement stitching.
 - Highly sensitive to external temperature fluctuations.
- New sensors must be developed to overcome these limitations
- Collaborative efforts with other synchrotron labs, with active participation of industrial vendors of x-ray optics and metrology instrumentation is necessary to advance metrology capabilities.

Roughness and Micro-stitching Interferometer

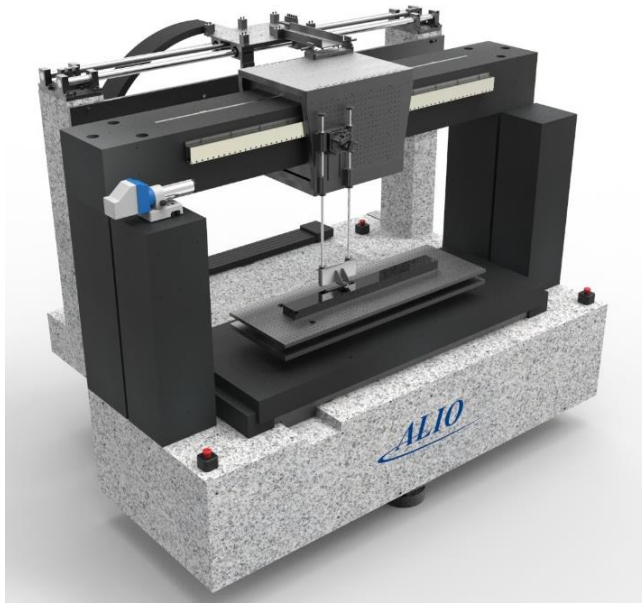


- 2-D surface profile measurements is essential for profile coating
- Fine resolution of height and lateral dimensions
- Limited to ~ 100 nm focus mirror with length < 100 mm

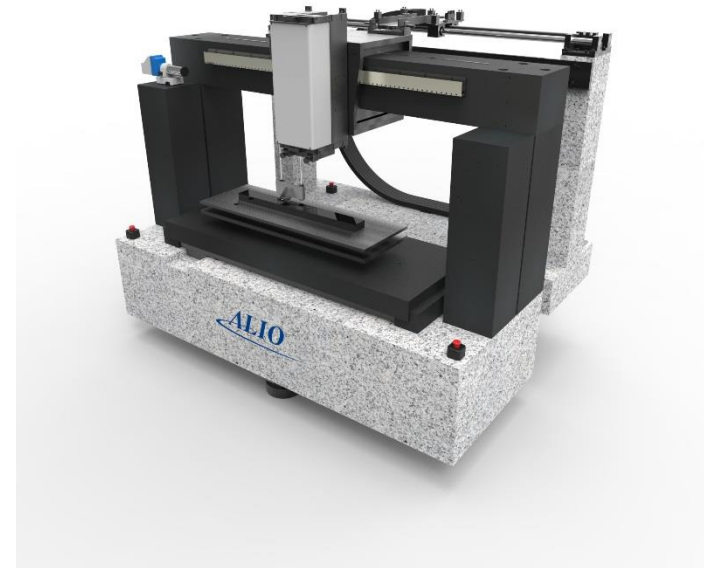
Achieving K-B mirrors with 50-nm focus requires an improved microstitching system to subnanometer figure error

Photo of the APS MicroXam RTS roughness & microstitching interferometer

Future development: 2-D dimensional surface profile measurement of large mirrors



Current sensor: Autocollimator



Future sensor: 2-D stitching

Summary

- The 4th generation light sources require advanced optics:
 - Mirror with unprecedented quality with slope error in the nrad range
 - Wavefront preserving optics for imaging
- Developing a new generation metrology tools is thus essential for both quality control and to support in-house optics fabrication and development.
- New metrology upgrades to support APS beamlines and APS-U include:
 - A new slope measuring profiler with <50 nrad rms resolution on flat mirrors up 1.5 m long.
- Future development:
 - Develop sensor/procedures for measuring curved optics
 - Implement a 2-D sensor with stitching for mirror up 1.5 m

Acknowledgements

Slope measuring profiler:

Jun Qian - Metrology measurements

Josef Sullivan - Data acquisition and control software

Mark Erdmann and Scott Izzo - Mechanical Engineering and design work

Curt Preissner - Vibration measurements

Jeff Collins - Temperature survey

John Sidarous, Andy Stevens, Marvin Kirshenbaum - Enclosure and cleanroom upgrades

Deming Shu – small angle generator design

Ben Sheff (Berkeley University, Summer Intern): Data processing software

Pet Jemian and Brian Toby support with data acquisition and analysis software

At-wavelength metrology

Shashi Marathe - Grating interferometry development

Xianbo Shi - Coherence measurements and simulation

Al Macrander and Stan Stoupin - 1-BM experiments

Erika Benda - Portable Grating interferometer Mechanical design

Dan Nocker - Grating interferometer assembling

Keenan Land and Kurt Goetze - motion electronics and control

APS/XSD management for support

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Thank you!